# Special Projective Motions in a Finsler Space 

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#### Abstract

In this paper, we consider a projective motion in a Finsler space whose deviation tensor satisfies certain conditions. It is proved that a projective motion in a Finsler space, whose deviation tensor satisfies $y^{k}\left(£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}\right)=0$, is necessarily an affine motion. It is also established that a projective motion which is also a curvature collineation and under which the covariant derivative of the deviation tensor is Lie-symmetric, is either an affine motion or the space is flat. In a recurrent Finsler space, if a projective motion is a curvature collineation and it leaves the recurrence vector invariant, then the projective motion is necessarily an affine motion.


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## 1. Introduction

K. Yano and T. Nagano ${ }^{1}$ discussed a Riemannian Space $V_{n}(n>2)$ admitting a projective motion under which the covariant derivative of Weyl's projective curvature tensor is invariant. They proved that such projective motion is an affine motion if the space is not of constant curvature. They also established that an infinitesimal projective motion in a symmetric Riemannian space $V_{n}(n>2)$ is an affine motion if the space is not of constant curvature. P. N. pandey ${ }^{2}$ extended these results to an $\mathrm{n}-$ dimensional Finsler space $F_{n}(n>2)$. He established that an infinitesimal projective motion which leaves the covariant derivative of projective deviation tensor invariant is an affine motion or the space is of scalar curvature. The aim of the present paper is to study an infinitesimal projective motion in a Finsler space, leaving certain tensors invariant.

## 2. Preliminaries

Let $F^{n}$ be an n-dimensional Finsler space equipped with a metric function $F\left(x^{i}, y^{i}\right)$ satisfying the requisite conditions ${ }^{2,3}$. Let $g_{i j}, G_{j k}^{i}$ and $H_{j k h}^{i}$ be the components of the metric tensor, Berwald's connection coefficients and components of Berwald's curvature tensor respectively. The curvature tensor $H_{j k h}^{i}$ is skew-symmetric in its last two lower indices and positively homogeneous of degree zero in $y^{i}$. Transvecting this tensor by $y^{i}$ we obtain the following tensors:
(a) $H_{k h}^{i}=H_{j k h}^{i} y^{j}$,
(b) $H_{h}^{i}=H_{k h}^{i} y^{k}$.

The tensor $H_{h}^{i}$ satisfies
(a) $\frac{1}{3}\left(\dot{\partial}_{k} H_{h}^{i}-\dot{\partial}_{h} H_{k}^{i}\right)=H_{k h,}^{i}$,
(b) $H_{i}^{i}=(\mathrm{n}-1) \mathrm{H}$,
(c) $y_{i} H_{h}^{i}=0$,
(d) $H_{h}^{i} y^{h}=0$,
where $H$ is scalar curvature, $y_{i}=g_{i k} y^{k}$ and $\dot{\partial}_{k}=\frac{\partial}{\partial y^{k}}$.
Partial differentiation of connection coefficients $G_{j k}^{i}$ with respect to $y^{h}$ yields a tensor being denoted by $G_{j k h}^{i}$, i.e $G_{j k h}^{i}=\dot{\partial}_{h} G_{j k}^{i}$. This tensor is symmetric in all its lower indices and satisfies

$$
\begin{equation*}
G_{j k h}^{i} y^{h}=0 . \tag{2.3}
\end{equation*}
$$

The commutation formula for Barwald covariant differential operator $B_{k}$ and directional differential operator $\dot{\partial}_{h}$ is given by

$$
\begin{equation*}
\dot{\partial}_{h} \mathrm{~B}_{k} T_{j}^{i}-\mathrm{B}_{k} \dot{\partial}_{h} T_{j}^{i}=T_{j}^{r} G_{h k r}^{i}-T_{r}^{i} G_{h k j}^{r}, \tag{2.4}
\end{equation*}
$$

where $T_{j}^{i}$ is an arbitrary tensor.
A Finsler space $F_{n}$ is said to be recurrent if there exists a non-zero vector $\lambda_{m}$ such that

$$
\begin{equation*}
B_{m} H_{j k h}^{i}=\lambda_{m} H_{j k h}^{i}, \quad H_{j k h}^{i} \neq 0 \tag{2.5}
\end{equation*}
$$

The vector $\lambda_{m}$ is called the recurrence vector. Pandey ${ }^{4}$ proved that the recurrence vector $\lambda_{m}$ is independent of directional arguments provided the scalar curvature $H$ does not vanish.

Let us consider an infinitesimal transformation

$$
\begin{equation*}
\bar{x}^{i}=x^{i}+\in v^{i}\left(x^{j}\right) \tag{2.6}
\end{equation*}
$$

where $\varepsilon$ is an infinitesimal constant and $v^{i}$ is a contravariant vector field and denote the operator for Lie differentiation with respect to the infinitesimal transformation (2.6) by the symbol $£$.
The commutation formula for the Lie-differential operator $£$ and Berwald covariant differential operator $B_{k}$ is given by

$$
\begin{equation*}
£ B_{k} T_{j}^{i}-B_{k} £ T_{j}^{i}=T_{j}^{r} £ G_{k r}^{i}-T_{r}^{i} £ G_{j k}^{r}-\left(\dot{\partial}_{r} T_{j}^{i}\right) £ G_{k}^{r}, \tag{2.7}
\end{equation*}
$$

while the commutation formula for the Lie-differential operator and directional differential operator is given by

$$
\begin{equation*}
\dot{\partial}_{k} £ T_{j}^{i}-£ \dot{\partial}_{k} T_{j}^{i}=0 \tag{2.8}
\end{equation*}
$$

where $T_{j}^{i}$ is an arbitrary tensor.
The infinitesimal transformation (2.6) is called an affine motion if it preserves parallelism of vectors while it is called a projective motion if it preserves geodesics.
The necessary and sufficient condition for the transformation (2.6) to be an affine motion is

$$
\begin{equation*}
£ G_{j k}^{i}=0, \tag{2.9}
\end{equation*}
$$

while the necessary and sufficient condition for (2.6) to be a projective motion is

$$
\begin{equation*}
£ G_{j k}^{i}=y^{i} p_{j k}+\delta_{j}^{i} p_{k}+\delta_{k}^{i} p_{j} \tag{2.10}
\end{equation*}
$$

where
(a) $p_{j}=\dot{\partial}_{j} p$,
(b) $p_{j k}=\dot{\partial}_{j} \dot{\partial}_{k} p$,
$p$ being a scalar invariant positively homogeneous of degree one in $y^{i}$. The homogeneity of $p_{\text {implies }}$

$$
\begin{equation*}
\text { (a) } p_{i} y^{i}=p, \quad \text { (b) } \quad p_{j k} y^{k}=0 \tag{2.12}
\end{equation*}
$$

It is well known that every affine motion is a projective motion. A nonaffine projective motion is characterized by (2.10), (2.11) and $p \neq 0$.
The necessary and sufficient condition for the transformation (2.6) to be a curvature collineation is

$$
\begin{equation*}
£ H_{j k h}^{i}=0 . \tag{2.13}
\end{equation*}
$$

## 3. A Special Projective Motion

Let a Finsler space $F^{n}$ admits an infinitesimal projective motion (2.6) characterized by (2.10) and (2.11).
Replacing $T_{j}^{i}$ in equation (2.7) by $H_{j}^{i}$, we have

$$
\begin{equation*}
£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}=H_{j}^{r} £ G_{r k}^{i}-H_{r}^{i} £ G_{j k}^{r}-\left(\dot{\partial}_{r} H_{j}^{i}\right) £ G_{k}^{r}, \tag{3.1}
\end{equation*}
$$

which, in view of (2.2 d), (2.10) and (2.12), gives

$$
\begin{align*}
£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i} & =y^{i} p_{r k} H_{j}^{r}+p_{r} H_{j}^{r} \delta_{k}^{i}-p_{j} H_{k}^{i} . \\
& -2 H_{j}^{i} p_{k}-p \dot{\partial}_{k} H_{j}^{i} \tag{3.2}
\end{align*}
$$

Transvecting (3.2) by $y^{k}$ and using (2.2 d), (2.12 ), we get

$$
\begin{equation*}
y^{k}\left[£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}\right]=y^{i} p_{r} H_{j}^{r}-4 p H_{j}^{i} . \tag{3.3}
\end{equation*}
$$

Suppose $y^{k}\left[£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}\right]=0$, then (3.3) gives

$$
\begin{equation*}
y^{i} p_{r} H_{j}^{r}-4 p H_{j}^{i}=0 \tag{3.4}
\end{equation*}
$$

Multiplying (3.4) by $y_{i}\left(=g_{i j} y^{j}\right)$, and using $y_{i} y^{i}=F^{2}$ and (2.2c), we get

$$
\begin{equation*}
p_{r} H_{j}^{r}=0 . \tag{3.5}
\end{equation*}
$$

Using (3.5) in (3.4), we find $p=0$, becasuese the deviation tensor $H_{j}^{i}$ of a non-flat Finsler space is non vanishing. This leads to

Theorem 3.1. A projective motion in a Finsler space $F_{n}$ is an affine motion if the following condition holds

$$
y^{k}\left[£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}\right]=0 .
$$

The condition $y^{k}\left[£ B_{k} H_{j}^{i}-B_{k} £ H_{j}^{i}\right]=0$ is obviously satisfied if the Lie differential operator $£$ and Berwald covariant differential operator $B_{k}$ commute. Thus, we have

Corollary 3.1. If the operator of Lie- differentiation with respect to a projective motion and Berwald covariant differentiation commute on Berwald deviation tensor, then the projective motion is necessarily an affine motion.

Suppose the projective motion (2.6) is a curvature collineation, i.e. (2.13) holds. Transvecting (2.13) by $y^{j} y^{k}$ and using (2.1), we get

$$
\begin{equation*}
£ H_{h}^{i}=0 . \tag{3.6}
\end{equation*}
$$

In view of (3.6), equations (3.2) becomes

$$
\begin{equation*}
£ B_{k} H_{j}^{i}=y^{i} p_{r k} H_{j}^{r}+p_{r} H_{j}^{r} \delta_{k}^{i}-p_{j} H_{k}^{i}-2 H_{j}^{i} p_{k}-p \dot{\partial}_{k} H_{j}^{i} . \tag{3.7}
\end{equation*}
$$

Interchanging the indices $j$ and $k$ in (3.7), we have

$$
\begin{equation*}
£ B_{j} H_{k}^{i}=y^{i} p_{r j} H_{k}^{r}+p_{r} H_{k}^{r} \delta_{j}^{i}-p_{k} H_{j}^{i}-2 H_{k}^{i} p_{j}-p \dot{\partial}_{j} H_{k}^{i} . \tag{3.8}
\end{equation*}
$$

Subtracting (3.8) from (3.7) and using (2.2a), we get

$$
\begin{align*}
£\left(B_{k} H_{j}^{i}-B_{j} H_{k}^{i}\right) & =\left(H_{j}^{r} p_{r k}-H_{k}^{r} p_{r j}\right) y^{i}+\left(H_{j}^{r} \delta_{k}^{i}-H_{k}^{r} \delta_{j}^{i}\right) p_{r}  \tag{3.9}\\
& +H_{k}^{i} p_{j}-H_{j}^{i} p_{k}-3 p H_{k j}^{i}
\end{align*}
$$

Suppose that the tensor $B_{k} H_{j}^{i}-B_{j} H_{k}^{i}=0$ is Lie-symmetric i.e. $£\left(B_{k} H_{j}^{i}-B_{j} H_{k}^{i}\right)=0$, then (3.9) gives

$$
\begin{align*}
\left(H_{j}^{r} p_{r k}-H_{k}^{r} p_{r j}\right) y^{i} & +\left(H_{j}^{r} \delta_{k}^{i}-H_{k}^{r} \delta_{j}^{i}\right) p_{r}+H_{k}^{i} p_{j} \\
& -H_{j}^{i} p_{k}-3 p H_{k j}^{i}=0 . \tag{3.10}
\end{align*}
$$

Transvecting (3.10) by $y^{k}$, and using (2.2d) and (2.12), we have

$$
\begin{equation*}
y^{i} p_{r} H_{j}^{r}-4 p H_{j}^{i}=0 \tag{3.11}
\end{equation*}
$$

Transvecting (3.11) by $y_{i}$ and using (2.2c), we have

$$
\begin{equation*}
p_{r} H_{j}^{r}=0, \tag{3.12}
\end{equation*}
$$

which together with (3.11) implies $p=0$ if $H_{j}^{i} \neq 0$ and $H_{j}^{i}=0$ if $p \neq 0$. This leads to

Theorem 3.2. A projective motion in a Finsler space $F_{n}$ which is a curvature collineation and with respect to which the covariant derivative of deviation tensor is Lie-symmetric, is either an affine motion or the space $F_{n}$ is flat.

If the Finsler space is a recurrent space characterized by (2.5), the condition

$$
\begin{equation*}
£\left(B_{k} H_{j}^{i}-B_{j} H_{k}^{i}\right)=0, \tag{3.13}
\end{equation*}
$$

may be written as

$$
\begin{equation*}
\left(£ \lambda_{k}\right) H_{j}^{i}-\left(£ \lambda_{j}\right) H_{k}^{i}=0 . \tag{3.14}
\end{equation*}
$$

Transvecting (3.14) by $y^{k}$, we have

$$
£\left(\lambda_{k} y^{k}\right) H_{j}^{i}=0,
$$

which implies $£\left(\lambda_{k} y^{k}\right)=0$ for $H_{j}^{i} \neq 0$. Differentiating $£\left(\lambda_{k} y^{k}\right)=0$ partially with respect to $y^{j}$, we get $£ \lambda_{j}=0$. Conversely, $£ \lambda_{j}=0$ implies (3.14) and hence (3.13). Thus, (3.13) is equivalent to $£ \lambda_{j}=0$. In view of this and theorem 3.2, we conclude

Theorem 3.3. A projective motion in a recurrent Finsler space, which is a curvature collineation and leaves the recurrence vector invariant, is necessarily an affine motion.

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