

## On Trans-Sasakian Manifolds

Vibha Srivastava and P. N. Pandey

Department of Mathematics

University of Allahabad, Allahabad-211002

Email: vibha.one22@rediffmail.com, pnpiaps@gmail.com

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**Abstract:** In the present paper, pseudo projectively flat and M-projectively flat trans-Sasakian manifolds are studied. It is proved that a trans-Sasakian manifold cannot be pseudo projectively flat unless  $(2n-1)(d\beta - \xi\beta\eta) + d\alpha\phi = 0$ .

If trans-Sasakian manifold is pseudo projectively flat then scalar curvature

$$r = \frac{-2n(2n+1)a}{(1-a)2nb-a^2}(\alpha^2 - \beta^2 - \xi\beta), \quad \text{where } \alpha \text{ and } \beta \text{ are related by}$$

$(2n-1)(d\beta - \xi\beta\eta) + d\alpha\phi = 0$ . It is also proved that a trans Sasakian manifold cannot be M-projectively flat unless  $(2n-1)\text{grad}\beta - \phi(\text{grad}\alpha) = (2n-1)(\xi\beta)\xi$ . If

trans-Sasakian manifold is M-projectively flat then scalar curvature  $r = 2n(2n+1)(\alpha^2 - \beta^2 - \xi\beta)$ , where  $\alpha$  and  $\beta$  are related by

$$(2n-1)\text{grad}\beta - \phi(\text{grad}\alpha) = (2n-1)(\xi\beta)\xi.$$

**Keywords:** Trans-Sasakian manifold, pseudo projectively flat manifold, M-projective curvature tensor.

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### 1. Introduction

J. A. Oubina<sup>1</sup> introduced a manifold which generalizes both  $\alpha$ -Sasakian and  $\beta$ -Kenmotsu manifolds. Such manifold was called a trans-Sasakian manifold of type  $(\alpha, \beta)$ . Trans-Sasakian manifolds of type  $(0, 0)$ ,  $(\alpha, 0)$  and  $(0, \beta)$  are called cosymplectic<sup>2</sup>,  $\alpha$ -Sasakian<sup>3,4</sup> and  $\beta$ -Kenmotsu<sup>3,5</sup> respectively. Concept of a nearly trans-Sasakian manifold was introduced by C. Gherghe<sup>6</sup>. Thus, Sasakian, Kenmotsu and cosymplectic manifold are particular cases of trans-Sasakian manifolds. J. C. Marrero<sup>7</sup> constructed three dimensional trans-Sasakian manifold. R. Prasad and V. Srivastava<sup>8</sup> obtained certain results on trans-Sasakian manifolds. Jeong- Sik kim et al.<sup>9</sup> studied a generalized Ricci-recurrent trans-Sasakian manifold.

In 2002, B. Prasad<sup>10</sup> defined a tensor field on a Riemannian manifold of dimension greater than 2 and he called it pseudo projective curvature tensor. This tensor is a generalisation of projective curvature tensor. Such tensor was studied on a  $\phi$ -recurrent Kenmotsu manifold by Venkatesha and C. S. Bagewadi<sup>11</sup>. C. S. Bagewadi, Venkatesha and N. S. Basavarajappa<sup>12</sup> studied such tensor on LP-Sasakian manifold while H. G. Nagaraja and G. Somashekhara<sup>13</sup> studied such tensor on a Sasakian manifold.

The pseudo projective curvature tensor on an  $n$ -dimensional Riemannian manifold is given by

$$(1.1) \quad P(X, Y)Z = R(X, Y)Z - \frac{1}{2(n-1)}b[S(Y, Z)X - S(X, Z)Y] \\ - \frac{r}{2n+1}\left(\frac{a}{2n} + b\right)[g(Y, Z)X - g(X, Z)Y],$$

where  $R$ ,  $S$ ,  $r$  and  $g$  are Riemannian curvature tensor, Ricci tensor, scalar curvature and metric of the Riemannian manifold respectively.

In 1971, G. P. Pokhariyal and R. S. Mishra<sup>14</sup> introduced a new curvature tensor in  $n$ -dimensional manifold denoted by  $W$  and defined by

$$(1.2) \quad W(X, Y)Z = R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y \\ + g(Y, Z)QX - g(X, Z)QY].$$

Such a tensor field  $W$  is known as  $M$ -projective curvature tensor.  $M$ -projective curvature tensor has been studied by J. P. Singh<sup>15</sup>, S. K. Chaubey and R. H. Ojha<sup>16</sup>, R. N. Singh and S. K. Pandey<sup>17</sup> and many others. In this paper we study pseudo-projectively flat and  $M$ -projectively flat trans-Sasakian manifolds.

## 2. Preliminaries

Let  $M$  be a  $(2n+1)$ -dimensional almost contact metric manifold<sup>18</sup> with almost contact metric structure  $(\phi, \xi, \eta, g)$  where  $\phi$  is a  $(1,1)$  tensor field,  $\xi$  is a vector field,  $\eta$  is a 1-form and  $g$  is a compatible Riemannian metric on  $M$  such that

$$(2.1) \quad \phi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \phi\xi = 0,$$

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$$

$$(2.3) \quad g(\phi X, Y) = g(X, \phi Y), \quad g(X, \xi) = \eta(X),$$

where  $X, Y \in TM$ .

An almost contact metric manifold is said to be contact manifold if

$$(2.4) \quad d\eta(X, Y) = \phi(X, Y) = g(X, \phi Y),$$

$\phi(X, Y)$  is being called fundamental 2-form on  $M$ .

An almost contact metric manifold  $M$  is called trans-Sasakian manifold if

$$(2.5) \quad (\nabla_x \phi)Y = \alpha \{g(X, Y)\xi - \eta(Y)X\} + \beta \{g(\phi X, Y)\xi - \eta(Y)\phi X\},$$

where  $\nabla$  is Levi-Civita connection of Riemannian metric  $g$  and  $\alpha$  &  $\beta$  are smooth functions on  $M$ . From equations (2.1), (2.2) and (2.3), we get

$$(2.6) \quad (\nabla_x \phi)\xi = -\alpha\phi X + \beta[X - \eta(X)\xi],$$

$$(2.7) \quad (\nabla_x \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y).$$

In a  $(2n+1)$ -dimensional trans-Sasakian manifold, we have

$$(2.8) \quad \begin{aligned} R(X, Y)\xi &= (\alpha^2 - \beta^2)[\eta(Y)X - \eta(X)Y] \\ &\quad + 2\alpha\beta[\eta(Y)\phi X - \eta(X)\phi Y] + (Y\alpha)\phi X \\ &\quad - (X\alpha)\phi Y + (Y\beta)\phi^2 X - (X\beta)\phi^2 Y, \end{aligned}$$

$$(2.9) \quad \begin{aligned} R(\xi, Y)X &= (\alpha^2 - \beta^2)[g(X, Y)\xi - \eta(X)Y] + (X\alpha)\phi Y \\ &\quad + 2\alpha\beta[g(\phi X, Y)\xi - \eta(X)\phi Y] + g(\phi X, Y)(grad \alpha) \\ &\quad + (X\beta)[Y - \eta(Y)\xi] - g(\phi X, \phi Y)(grad \beta), \end{aligned}$$

$$(2.10) \quad \eta(R(\xi, Y)X) = g(R(\xi, Y)X, \xi) \\ = (\alpha^2 - \beta^2 - \xi\beta)[g(X, Y) - \eta(X)\eta(Y)],$$

$$(2.11) \quad 2\alpha\beta + \xi\alpha = 0,$$

$$(2.12) \quad S(X, \xi) = (2n(\alpha^2 - \beta^2) - \xi\beta)\eta(X) - (2n-1)X\beta - (\phi X)\alpha$$

and

$$(2.13) \quad Q\xi = (2n(\alpha^2 - \beta^2) - \xi\beta)\xi - (2n-1)(\text{grad}\beta) + \phi(\text{grad}\alpha).$$

An almost contact metric manifold  $M$  is said to be  $\eta$ -Einstein if its Ricci-tensor  $S$  is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y),$$

where  $a$  and  $b$  are smooth functions on  $M$ . An  $\eta$ -Einstein manifold becomes Einstein manifold if  $b = 0$ , i. e.

$$S(X, Y) = ag(X, Y).$$

If  $\{e_1, e_2, \dots, e_{2n}, e_{2n+1} = \xi\}$  be a local ortho-normal basis of tangent space in a  $(2n+1)$ -dimensional almost contact manifold  $M$ , then we have

$$\sum_{i=1}^{2n+1} g(X, Y) = 2n+1.$$

$$\sum_{i=1}^{2n+1} g(e_i, Y)S(X, e_i) = \sum_{i=1}^{2n+1} R(e_i, Y, X, e_i) \\ = S(X, Y).$$

### 3. Pseudo Projectively Flat and M-Projectively Flat Manifolds

Let  $M$  be a  $(2n+1)$ -dimensional Pseudo projectively flat manifold, then from equation (1.1) we have

$$(3.1) \quad aR(X, Y)Z = b[S(X, Z)Y - S(Y, Z)X]$$

$$+ \frac{r}{2n+1} \left( \frac{a}{2n} + b \right) [g(Y, Z)X - g(X, Z)Y].$$

Contracting equation (3.1) with  $U$ , we get

$$(3.2) \quad \begin{aligned} g(R(X, Y)Z, U) = & \frac{b}{a} [S(X, Z)g(Y, U) - S(Y, Z)g(X, U)] \\ & + \frac{r}{(2n+1)a} \left( \frac{a}{2n} + b \right) [g(Y, Z)g(X, U) \\ & - g(X, Z)g(Y, U)]. \end{aligned}$$

Let  $\{e_1, e_2, \dots, e_{2n}, e_{2n+1} = \xi\}$  be a local ortho-normal basis of tangent space. Putting  $Y = Z = e_i$ , in equation (3.2), we get

$$(3.3) \quad S(X, U) = \frac{r}{2n+1} g(X, U),$$

for  $a \neq b$ .

Hence a pseudo projectively flat manifold is Einstein manifold if  $a \neq b$ .

If the manifold is  $M$ - projectively flat then from equation (1.2), we have

$$(3.4) \quad \begin{aligned} R(X, Y)Z = & \frac{1}{4n} [S(Y, Z)X - S(X, Z)Y \\ & + g(Y, Z)QX - g(X, Z)QY]. \end{aligned}$$

Contracting equation (3.4) with  $U$ , we get

$$(3.5) \quad \begin{aligned} g(R(X, Y)Z, U) = & \frac{1}{4n} [S(Y, Z)g(X, U) - S(X, Z)g(Y, U) \\ & + g(Y, Z)S(X, U) - g(X, Z)S(Y, U)]. \end{aligned}$$

Let  $\{e_1, e_2, \dots, e_{2n}, e_{2n+1} = \xi\}$  be a local ortho-normal basis of tangent space. Putting  $Y = Z = e_i$ , in equation (3.5), we get

$$(3.6) \quad S(X, U) = \frac{r}{2n+1} g(X, U).$$

Hence an  $M$ - projectively flat manifold is Einstein manifold.

#### 4. Pseudo Projectively Flat Trans-Sasakian Manifold

If a trans-Sasakian manifold is Pseudo projectively flat then from equation (1.1), we have

$$(4.1) \quad \begin{aligned} aR(X, Y)Z &= b[S(X, Z)Y - S(Y, Z)X] \\ &+ \frac{r}{2n+1} \left( \frac{a}{2n} + b \right) [g(Y, Z)X - g(X, Z)Y]. \end{aligned}$$

Contracting equation (4.1) with  $U$ , we get

$$(4.2) \quad \begin{aligned} g(R(X, Y)Z, U) &= \frac{b}{a} [S(X, Z)g(Y, U) - S(Y, Z)g(X, U)] \\ &+ \frac{r}{(2n+1)a} \left( \frac{a}{2n} + b \right) [g(Y, Z)g(X, U) - g(X, Z)g(Y, U)]. \end{aligned}$$

Putting  $U = \xi$  and using equation (4.2), we get

$$(4.3) \quad \begin{aligned} g(R(X, Y)Z, \xi) &= \frac{b}{a} [S(X, Z)\eta(Y) - S(Y, Z)\eta(X)] \\ &+ \frac{r}{(2n+1)a} \left( \frac{a}{2n} + b \right) [g(Y, Z)\eta(X) - g(X, Z)\eta(Y)]. \end{aligned}$$

Putting  $X = \xi$  and using equations (2.3), (2.10) and (2.12), we get

$$(4.4) \quad \begin{aligned} S(Y, Z) &= \left[ \frac{ra}{2n+1} \left( \frac{a}{2n} + b \right) - \frac{a}{b} (\alpha^2 - \beta^2 - \xi\beta) \right] (Y, Z) \\ &+ \left[ \frac{a}{b} (\alpha^2 - \beta^2 - \xi\beta) - (2n(\alpha^2 - \beta^2) - \xi\beta) \right. \\ &\quad \left. - \frac{ra}{(2n+1)} \left( \frac{a}{2n} + b \right) \right] \eta(Y)\eta(Z) + (2n-1)Z\beta + (\phi Z)\alpha\eta(Y). \end{aligned}$$

From equations (3.3) and (4.4), we have

$$(4.5) \quad r = \frac{-2n(2n+1)a}{(1-a)2nb-a^2}(\alpha^2 - \beta^2 - \xi\beta)$$

and

$$(4.6) \quad (2n-1)(d\beta - \xi\beta\eta) + d\alpha\phi = 0.$$

**Theorem 4.1:** *A trans-Sasakian manifold cannot be pseudo projectively flat unless  $(2n-1)(d\beta - \xi\beta\eta) + d\alpha\phi = 0$ .*

From equations (4.5) and (4.6), we get

**Theorem 4.2:** *The scalar curvature  $r$  of a pseudo projectively flat trans-Sasakian manifold satisfies*

$$(4.7) \quad r = \frac{-2n(2n+1)a}{(1-a)2nb-a^2}(\alpha^2 - \beta^2 - \xi\beta),$$

where  $\alpha$  and  $\beta$  are related by  $(2n-1)(d\beta - \xi\beta\eta) + d\alpha\phi = 0$ .

## 5. $M$ -Projectively Flat Trans-Sasakian Manifolds

Let a trans-Sasakian manifold be  $M$ -projectively flat. From equation (1.2), we have

$$(5.1) \quad R(X, Y)Z = \frac{1}{4n} [S(Y, Z)X - S(X, Z)Y \\ + g(Y, Z)QX - g(X, Z)QY].$$

Contracting equation (5.1) with  $U$ , we get

$$(5.2) \quad g(R(X, Y)Z, U) = \frac{1}{4n} [S(Y, Z)g(X, U) - S(X, Z)g(Y, U) \\ + g(Y, Z)S(X, U) - g(X, Z)S(Y, U)].$$

Putting  $U = \xi$  in equation (5.2) and using equations (2.3), we have

$$(5.3) \quad g(R(X, Y)Z, \xi) = \frac{1}{4n} [S(Y, Z)\eta(X) - S(X, Z)\eta(Y) \\ + g(Y, Z)S(X, \xi) - g(X, Z)S(Y, \xi)].$$

Again putting  $X = \xi$  in equation (5.3) and using equations (2.3), (2.10) and (2.12), we have

$$(5.4) \quad 4n(\alpha^2 - \beta^2 - \xi\beta)[g(Y, Z) - \eta(Y)\eta(Z)] = S(Y, Z) + \{2n(\alpha^2 - \beta^2) \\ - \xi\beta\}\eta(Y)\eta(Z) - (2n-1)Z\beta\eta(Y) - (\phi Z)\alpha\eta(Y) \\ + 2n(\alpha^2 - \beta^2 - \xi\beta)g(Y, Z) - \{2n(\alpha^2 - \beta^2) \\ - \xi\beta\}\eta(Y)\eta(Z) + (2n-1)Y\beta\eta(Z) + (\phi Y)\alpha\eta(Z),$$

$$(5.5) \quad S(Y, Z) = 2n(\alpha^2 - \beta^2 - \xi\beta)g(Y, Z) - 4n(\alpha^2 - \beta^2 - \xi\beta)\eta(Y)\eta(Z) \\ + (2n-1)Z\beta\eta(Y) + (\phi Z)\alpha\eta(Y) - (2n-1)Y\beta\eta(Z) \\ - (\phi Y)\alpha\eta(Z).$$

From equations (3.6) and (5.5), we get

$$(5.6) \quad r = 2n(2n+1)(\alpha^2 - \beta^2 - \xi\beta)$$

and

$$(5.7) \quad (2n-1)\text{grad}\beta - \phi(\text{grad}\alpha) = (2n-1)(\xi\beta)\xi.$$

**Theorem 5.1:** *A trans-Sasakian manifold cannot be M-projectively flat unless  $(2n-1)\text{grad}\beta - \phi(\text{grad}\alpha) = (2n-1)(\xi\beta)\xi$ .*

From equations (5.6) and (5.7), we have

**Theorem 5.2:** *If a trans-Sasakian manifold is M-projectively flat then scalar curvature  $r = 2n(2n+1)(\alpha^2 - \beta^2 - \xi\beta)$ , where  $\alpha$  and  $\beta$  are related by  $(2n-1)\text{grad}\beta - \phi(\text{grad}\alpha) = (2n-1)(\xi\beta)\xi$ .*



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