

On Para-Sasakian Manifolds

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Abstract: In this paper, we have studied the properties of Curvature tensor in a para-sasakian manifolds and the condition that if p-sasakian manifold M is concircularly flat, then $V(\xi, X)S = 0$. It has also been obtained that the p-sasakian manifolds is of constant curvature if $R(\xi, X)R = 0$, where V , R and S are the concircular, Riemannian and Ricci curvature tensors respectively, ξ is a characteristic vector field and $X \in TM$.

Key words: p-sasakian manifold, curvature tensors.

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1. Introduction

Let M^n be an n -dimensional C^∞ manifolds. If there exists a tensor field F of type $(1, 1)$, a vector field ξ and a 1-form η in M^n satisfying

$$(1.1) \quad \bar{\bar{X}} = X - \eta(X)\xi, \quad \bar{X} = F(X), \quad \eta(\xi) = 1.$$

Then M^n is called an almost para-contact manifold. Let g be the Riemannian metric satisfying

$$(1.2) \quad g(X, \xi) = \eta(X),$$

$$(1.3) \quad \eta(FX) = 0, \quad F\xi = 0, \quad \text{rank } F = (n-1),$$

$$(1.4) \quad g(FX, FY) = g(X, Y) - \eta(X)\eta(Y).$$

Then the set (F, ξ, η, g) satisfying (1.1), (1.2), (1.3) and (1.4) is called an almost para-contact Riemannian structure. The manifold with such structure is called an almost para-contact Riemannian manifold¹.

If we define $\nabla F(X, Y) = g(\bar{X}, Y)$, then in addition to the above relations the following are satisfied

$$(1.5) \quad \nabla F(X, Y) = \nabla F(Y, X),$$

$$(1.6) \quad \nabla F(\bar{X}, \bar{Y}) = \nabla F(X, Y).$$

Let us consider an n -dimensional differentiable manifold M with a positive definite metric g which admits 1-forms η satisfying

$$(1.7) \quad (\nabla_{X\eta})(Y) - (\nabla_{Y\eta})(X) = 0,$$

and

$$(1.8) \quad (\nabla_X \nabla_{Y\eta})(Z) = -g(X, Z)\eta(Y) - g(X, Y)\eta(Z) + 2\eta(X)\eta(Y)\eta(Z),$$

where ∇ denote the covariant differentiation with respect to g .

Moreover, if we put

$$(1.9) \quad \eta(X) = g(X, \xi) \quad \text{and} \quad \nabla_{X\xi} = \bar{X}.$$

Then it can be easily verified that the manifold in consideration becomes an almost para-contact Riemannian manifold. Such a manifold is called a p-sasakian manifold². For a p-sasakian manifold the following relations hold

$$(1.10) \quad R(X, Y)\xi = \eta(X)Y - \eta(Y)X,$$

$$(1.11) \quad R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi,$$

$$(1.12) \quad R(\xi, X)\xi = X - \eta(X)\xi,$$

$$(1.13) \quad S(\xi, X) = -(n-1)\eta(X),$$

$$(1.14) \quad Q\xi = -(n-1)\xi,$$

$$(1.15) \quad \eta(R(X, Y)Z) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X),$$

$$(1.16) \quad \eta(R(X, Y)\xi) = 0,$$

$$(1.17) \quad \eta(R(\xi, X)Y) = \eta(X)\eta(Y) - g(X, Y),$$

where R and S are the curvature tensors and Ricci tensors and Q is the Ricci operator.

An almost para-contact Riemannian manifold M is said to be η -Einstein³ if the Ricci tensor S is of the form $S = ag + b\eta \otimes \xi$, where a and b are smooth functions on M . In this case, we have

$$(1.18) \quad S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y).$$

In particular, if $b=0$, then M is an Einstein manifold. For any vector field X, Y, Z if S is the Ricci curvature and Q is the Ricci operator, then

$$S(X, Y) = g(QX, Y).$$

2. Curvature Tensors

By definition the concircular curvature tensor V and the projective curvature tensor P are given by

$$(2.1) \quad V(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y]$$

and

$$(2.2) \quad P(X, Y)Z = R(X, Y)Z - \frac{1}{(n-1)}[S(Y, Z)X - S(X, Z)Y],$$

where R and r are Riemannian curvature tensor and scalar curvature of M^n respectively.

The endomorphisms $X \wedge Y$, $X \wedge_s Y$ and the homeomorphism $R(X, \xi)R$ are defined by

$$(2.3) \quad (X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y,$$

$$(2.4) \quad (X \wedge_s Y)Z = S(Y, Z)X - S(X, Z)Y,$$

$$(2.5) \quad (R(X, \xi)R)(U, Z)W = R(X, \xi)R(U, Z)W - R(R(X, \xi, U)Z)W \\ - R(U, R(X, \xi, Z)W) - R(U, Z)R(X, \xi, W).$$

If we take $(R(X, \xi)R)(U, Z)W = 0$, then from (2.5), we have

$$(2.6) \quad R(X, \xi)R(U, Z)W - R(R(X, \xi, U)Z)W - R(U, R(X, \xi, Z)W) \\ - R(U, Z)R(X, \xi, W) = 0.$$

Putting $U = \xi$ in (2.6) and using (1.11) and (1.12), we have

$$R(X, Z, W) = g(X, W)Z - g(Z, W)X.$$

By suitable contraction, we have

$$r = -n(n-1).$$

Thus we can state the following theorem

Theorem (2.1): *If a p-Sasakian manifold satisfies the conditions*

$$(R(X, \xi)R)(U, Z)W = 0,$$

then the manifold is of constant curvature.

Theorem (2.2): *If a p-Sasakian manifold M^n is concircularly flat, then the scalar curvature $r = -n(n-1)$.*

Proof: As M^n is concircularly flat, $V(X, Y, Z)$ vanishes identically and from (2.1), we have

$$R(X, Y, Z) = \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y],$$

$$R(X, Y, Z, U) = \frac{r}{n(n-1)}[g(Y, Z)g(X, U) - g(X, Z)g(Y, U)].$$

Putting $X = U = \xi$ and using (1.11) and (1.4), we get

$$\left[1 + \frac{r}{n(n-1)}\right]g(FY, FZ) = 0.$$

Now, $g(FY, FZ) = 0$ is not possible in general since g is non-singular and this proves the theorem.

We now state the following results as a corollary of Theorem (2.2)

Corollary (2.1): *A concircularly flat p-Sasakian manifold is necessarily a manifold of constant curvature-1.*

Theorem (2.3): *An n-dimensional p-Sasakian manifold M satisfies*

$V(\xi, X).S = 0$ if and only if either M has a scalar curvature $r = -n(n-1)$ or M is an Einstein manifold with the scalar curvature $r = -n(n-1)$.

Proof: The condition $V(\xi, X).S = 0$ implies that

$$(2.7) \quad S(V(\xi, X)Y, \xi) + S(Y, V(\xi, X)\xi) = 0.$$

Now from (2.1) and (1.8), we have

$$\left[1 + \frac{r}{n(n-1)}\right](-g(X, Y)S(\xi, \xi) + \eta(Y)S(X, \xi) - \eta(X)S(Y, \xi) + S(X, Y)) = 0.$$

Using (2.13), we get

$$\left[1 + \frac{r}{n(n-1)}\right](S - (1-n)g) = 0.$$

Therefore either the scalar curvature r of M is $r = -n(n-1)$, which is of constant curvature or $S = (1-n)g$ which implies that M is an Einstein manifold with the scalar curvature $r = -n(n-1)$. The converse statement of the theorem is trivial.

Using the fact of theorem (2.2) that a p -Sasakian manifold is concircularly flat then the scalar curvature $r = -n(n-1)$. We have following corollary of Theorem (2.3).

Corollary (2.2): If a p -Sasakian manifold M^n is concircularly flat then $V(\xi, X).S = 0$.

3. p -Sasakian Manifold satisfying $R(\xi, X)S = 0$

Let $(R(X, \xi)S)(Y, Z) = 0$, implies that

$$S(R(X, \xi)Y, Z) + S(Y, R(X, \xi)Z) = 0.$$

Putting $Z = \xi$ and using (1.11), (1.12) and (1.13), we get

$$(3.1) \quad S(X, Y) = -(n-1)g(X, Y).$$

Hence the scalar curvature $r = -n(n-1)$, which gives

$$S(X, Y) = \frac{r}{n}g(X, Y).$$

i.e. M is an Einstein Manifold.

Thus we can state the following theorem:

Theorem (3.1): *If a p - Sasakian manifold satisfies the condition*

$$(R(X, \xi)S)(Y, Z) = 0,$$

Then the manifold is an Einstein manifold.

Corollary (3.1): *If a p - Sasakian manifold is an Einstein manifold the scalar curvature r has a constant value equal to $-n(n-1)$.*

Definition (3.1): A para- Sasakian manifold M satisfying

$$(3.2) \quad S(X, Y) = b g(X, Y) - c g(FX, Y),$$

where b is a constant and c is a function on M , is called a p -Einstein manifold.

Theorem (3.2): *A p - Sasakian manifold M is a para- Einstein manifold if and only if*

$$(R(X, \xi)S)(Y, Z) = -c[\eta(Z)g(FY, X) + \eta(Y)g(FX, Z)].$$

Proof: we have,

$$(3.3) \quad (R(X, \xi)S)(Y, Z) = -S(R(X, \xi)Y, Z) - S(Y, R(X, \xi)Z).$$

Let M be a para- Einstein. Then using (3.2), we get

$$(3.4) \quad \begin{aligned} S(R(X, \xi)Y, Z) &= b\eta(Z)g(X, Y) + c\eta(Y)g(FX, Z) \\ &\quad - b\eta(Y)g(X, Z) \end{aligned}$$

and

$$(3.5) \quad \begin{aligned} S(Y, R(X, \xi)Z) &= b\eta(Y)g(X, Z) + c\eta(Z)g(FY, X) \\ &\quad - b\eta(Z)g(Y, X). \end{aligned}$$

Using (3.4), (3.5) in (3.3), we get

$$(3.6) \quad (R(X, \xi)S)(Y, Z) = -c[\eta(Z)g(FY, X) + \eta(Y)g(FX, Z)].$$

Conversely, let (3.6) hold, then putting $Z = \xi$ in (3.6), we get

$$-S(R(X, \xi)Y, \xi) - S(Y, R(X, \xi)\xi) = -cg(FY, X),$$

$$(n-1)g(X, Y) + S(Y, X) = -cg(FY, X),$$

$$S(Y, X) = -(n-1)g(X, Y) - c'F(Y, X),$$

which shows that M is a para- Einstein manifold.

From Theorem (3.1) a p-Sasakian manifold satisfying the conditions $R(X, \xi)S=0$, is an Einstein manifold. This condition and Theorem (3.2) give $c = 0$, and thus a para- Einstein manifold reduces to Einstein manifold.

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