

On $*gs$ -Closed Sets in Bitopological Spaces

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Abstract: In this paper, we introduce $*gs$ -closed sets in bitopological spaces. Properties of these sets are investigated and we introduce new bitopological spaces (i, j) - T_s , (i, j) - T_s^* and (i, j) - $*T_s$ spaces as applications. Further we introduce and study $*gs$ -continuity in bitopological spaces.

Key Words: (i, j) - $*gs$ -closed sets; (i, j) - T_s spaces; (i, j) - T_s^* spaces and (i, j) - $*T_s$ spaces; $*DS$ (i, j) -continuity.

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1. Introduction

A triple (X, τ_1, τ_2) where X is non empty set and τ_1, τ_2 are two topologies on X is called a bitopological space. Kelly¹ initiated and study such spaces in 1985. Fukutaka² introduced the concept of g -closed sets³ in bitopological spaces. Sheik John and Sundram⁴ introduced the concept of g^* -closed sets in bitopological spaces and after that many authors turned their attention towards generalizations of various concepts of topology by considering bitopological spaces. Recently Agarwal, Garg and Goel⁵ introduced and studied the concepts of $*gs$ -closed sets and $*gs$ -continuity in topological spaces. In this paper, we introduce the concepts of $*gs$ -closed sets and $*gs$ -continuity for bitopological spaces and then investigate three new bitopological spaces (i, j) - T_s space, (i, j) - T_s^* space and (i, j) - $*T_s$ space.

2. Preliminaries

If A is a subset of X with a topology τ , then the closure of A is denoted by $\tau\text{-cl}(A)$ or $\text{cl}(A)$, the interior of A is denoted by $\tau\text{-int}(A)$ or $\text{int}(A)$ and the complement of A is denoted by A^c .

Definition 2.1: (i) A subset A of a topological space (X, τ) is called semi-open⁶, (resp. regular open⁷, pre-open³) if $A \subseteq \text{cl}(\text{int}(A))$ (resp. $A = \text{int}(\text{Cl}(A))$, $A \subseteq \text{int}(\text{cl}(A))$).

(ii) Subset A of a topological space (X, τ) is called a generalized closed set³ (briefly g -closed set) (resp. $\hat{g}$ -closed set⁸, $*g$ -closed set⁹, $*gs$ -closed set¹⁰) if $\text{cl}(A) \subseteq U$ (resp. $\text{cl}(A) \subseteq U$, $\text{scl}(A) \subseteq U$) whenever $A \subseteq U$ and U is open (resp. semi-open, $\hat{g}$ -open, $\hat{g}$ -open) in X .

Definition 2.2: The intersection of all pre-closed (resp. semi-closed) sets containing A is called the pre-closure (resp. semi-closure) of A and it is denoted by $\text{pcl}(A)$ (resp. $\text{scl}(A)$).

Throughout this paper, X and Y represent non-empty bi-topological spaces (X, τ_1, τ_2) and (Y, σ_1, σ_2) on which no separation axioms are assumed unless otherwise explicitly mentioned and integers $i, j, k \in \{1, 2\}$. For a subset A of X , $\tau_i\text{-cl}(A)$ (resp. $\tau_i\text{-int}(A)$, $\tau_i\text{-pcl}(A)$) denote the closure (resp. interior, preclosure) of A w.r.t. topology τ_i . We denote the family of all $\hat{g}$ -open subsets of X w.r.t. topology τ_i by $\hat{G}O(X, \tau_i)$ and the family of all τ_j -closed sets is denoted by F_j . By (i, j) we mean the pair of topologies (τ_i, τ_j) .

Definition 2.3: A subset A of a bitopological space (X, τ_1, τ_2) is called :

- (i) (i, j) - g -closed² if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and $U \in \tau_i$.
- (ii) (i, j) - rg -closed¹¹ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is regular open in τ_i .
- (iii) (i, j) - gpr -closed¹² if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is regular open in τ_i .
- (iv) (i, j) - Wg -closed¹³ if $\tau_j\text{-cl}(\tau_i\text{-int}(A)) \subseteq U$ whenever $A \subseteq U$ and $U \in \tau_i$.
- (v) (i, j) - ω -closed¹² if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is semi-open in τ_i .
- (vi) (i, j) - g^* -closed⁴ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is generalized-open in τ_i .
- (vii) (i, j) - $*g$ -closed¹⁴ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is $\hat{g}$ -open in τ_i .

(viii) (i, j) - $\hat{g}$ -closed¹⁵ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is sg-open in τ_i .

The family of all (i, j) -g-closed (resp. (i, j) -rg-closed, (i, j) -gpr-closed, (i, j) -Wg-closed, (i, j) - ω -closed, (i, j) - $g^\ast$ -closed, (i, j) - $\ast$ g-closed, (i, j) - $\hat{g}$ -closed) subsets of a bitopological space (X, τ_1, τ_2) is denoted by $D(i, j)$ (resp. $Dr(i, j)$, $\zeta(i, j)$, $W(i, j)$, $C(i, j)$ and $D^\ast(i, j)$, $\ast D(i, j)$, $\hat{D}(i, j)$).

Definition 2.4

- (i) A bitopological space (X, τ_1, τ_2) is said to be (i, j) - $T_{1/2}$ ² (resp. (i, j) - $T^\ast_{1/2}$, (i, j) - $\ast T_{1/2}$, (i, j) - $\ast gT^\ast_{1/2}$, (i, j) - $\ast g^\ast T_{1/2}$, (i, j) - $\hat{T}_{1/2}$ space) if every (i, j) -g-closed (resp. (i, j) - $g^\ast$ -closed, (i, j) -g-closed, (i, j) - $\ast$ g-closed, (i, j) -g-closed, (i, j) - $\hat{g}$ -closed) sets is τ_j -closed (resp. τ_j -closed, (i, j) - $g^\ast$ -closed, τ_j -closed, (i, j) - $\ast$ g-closed, τ_j -closed)^{4,14,15}.
- (ii) Bitopological space (X, τ_1, τ_2) is said to be strongly pairwise- $T_{1/2}$ (resp. strongly pairwise $T^\ast_{1/2}$, strongly pairwise $\ast gT^\ast_{1/2}$) space if it is $(1, 2)$ - $T_{1/2}$ and $(2, 1)$ - $T_{1/2}$ (resp. $(1, 2)$ - $T^\ast_{1/2}$ and $(2, 1)$ - $T^\ast_{1/2}$, $(1, 2)$ - $\ast gT^\ast_{1/2}$ and $(2, 1)$ - $\ast gT^\ast_{1/2}$ space)^{2,4,14}.

Definition 2.5: A map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called :

- (i) τ_j - σ_k -continuous¹⁶ if $f^{-1}(V) \in \tau_j$ for every $V \in \sigma_k$.
- (ii) $D(i, j)$ - σ_k -continuous¹⁶ (resp. $Dr(i, j)$ - σ_k -continuous¹¹, $\zeta(i, j)$ - σ_k -continuous¹², $W(i, j)$ - σ_k -continuous¹³, $C(i, j)$ - σ_k -continuous¹² and $D^\ast(i, j)$ - σ_k -continuous⁴, $\ast D(i, j)$ - σ_k -continuous¹⁴, $\hat{D}(i, j)$ - σ_k -continuous¹⁵) if the inverse image of every σ_k -closed set is (i, j) -g-closed (resp. (i, j) -rg-closed, (i, j) -gpr-closed, (i, j) -wg-closed, (i, j) - ω -closed and (i, j) - $g^\ast$ -closed, (i, j) - $\ast$ g-closed, (i, j) - $\hat{g}$ -closed,) set in (X, τ_1, τ_2) .

2. (i, j) - $\ast$ gs-Closed Sets

In this section we introduce the concepts of (i, j) - $\ast$ gs-closed sets in bitopological spaces.

Definition 3.1: A subset A of a bitopological space (X, τ_1, τ_2) is said to be an (i, j) - $\ast$ gs-closed set if $\tau_j\text{-scl}(A) \subseteq U$ whenever $A \subseteq U$ and $U \in \hat{G}O(X, \tau_i)$.

We denote the family of all (i, j) - $\ast$ gs-closed sets in (X, τ_1, τ_2) by $\ast DS(i, j)$.

Remark 3.2: By setting $\tau_1 = \tau_2$ in definition (3.1.1), an (i, j) -*gs-closed set is a *gs-closed set.

Proposition 3.3: If A is τ_j -sclosed and so τ_j -closed subset of (X, τ_1, τ_2) , then A is (i, j) -*gs-closed.

The converse of the above proposition is not necessarily true as seen from following example.

Example 3.4: Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{c\}, \{a, c\}, X\}$ and $\tau_2 = \{\emptyset, \{a\}, X\}$. Here the subset $\{a, b\}$ is $(1, 2)$ -*gs-closed but not τ_2 -sclosed and τ_2 -closed in (X, τ_1, τ_2) .

Proposition 3.5: In a bitopological space every (i) (i, j) -g*-closed set (ii) (i, j) -*g-closed set (iii) (i, j) - $\hat{g}$ -closed set is (i, j) -*gs-closed set.

The following examples show that the reverse implications of the above proposition are not true.

Example 3.6: Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\emptyset, \{a\}, \{b, c\}, X\}$ then the subset $\{b\}$ is $(2, 1)$ -*gs-closed but not $(2, 1)$ -g*-closed.

Example 3.7: Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{b, c\}, X\}$, $\tau_2 = \{\emptyset, \{a\}, \{a, b\}, X\}$ then the subset $\{b\}$ is $(1, 2)$ -*gs-closed but not $(1, 2)$ -*g-closed.

Example 3.8: Let $X = \{a, b, c, d\}$, $\tau_1 = \{\emptyset, \{a, b\}, X\}$, $\tau_2 = \{\emptyset, \{a\}, \{a, b, c\}, X\}$ then the subset $\{b, d\}$ is $(2, 1)$ -*gs-closed but not $(2, 1)$ - $\hat{g}$ -closed.

Remark 3.9: The following examples show that (i, j) -*gs-closed set is independent from (i) (i, j) -g-closed set (ii) (i, j) -rg-closed set (iii) (i, j) -gpr-closed set (iv) (i, j) - ω -closed set (v) (i, j) -s-closed set (vi) (i, j) -wg-closed set, (vii) (i, j) -sg-closed set.

Example 3.10: In example (3.4), the subset $\{c\}$ is $(1, 2)$ -*gs-closed but not $(1, 2)$ -g-closed.

Example 3.11: In example (3.7), the subset $\{a, b\}$ is $(1, 2)$ -g-closed but not $(1, 2)$ -*gs-closed.

Example 3.12: In example (3.6), the subset $\{a\}$ is $(2, 1)$ -*gs-closed but not $(2, 1)$ -rg-closed. Also $\{a, b\}$ is $(2, 1)$ -rg-closed but not $(2, 1)$ -*gs-closed.

Example 3.13: Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{a, c\}, X\}$, $\tau_2 = \{\emptyset, \{a, b\}, X\}$, the subset $\{a, c\}$ is $(1, 2)$ -gpr-closed but not $(1, 2)$ -*gs-closed.

Example 3.14: In example (3.6), the subset $\{a\}$ is $(2, 1)$ -*gs-closed but not $(2, 1)$ -gpr-closed.

Example 3.15: Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, X\}$, $\tau_2 = \{\phi, \{b\}, X\}$ the subset $\{a, b\}$ is $(1, 2)$ -*gs-closed but not $(1, 2)$ - ω -closed.

Example 3.16: Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, X\}$, $\tau_2 = \{\phi, \{b\}, \{a, c\}, X\}$, the subset $\{a, b\}$ is $(2, 1)$ - ω -closed but not $(2, 1)$ -*gs-closed.

Example 3.17: In example (3.4), the subset $\{a\}$ is $(1, 2)$ -s-closed but not $(1, 2)$ -*gs-closed.

Example 3.18: Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\tau_2 = \{\emptyset, \{a, b\}, X\}$, the subset $\{a, b\}$ is $(2, 1)$ -*gs-closed but not $(2, 1)$ -s-closed.

Example 3.19: In example (3.7), the subset $\{a, b\}$ is $(1, 2)$ -*gs-closed but not $(1, 2)$ -wg-closed.

Example 3.20: In example (3.18), the subset $\{a\}$ is $(1, 2)$ -wg-closed but not $(1, 2)$ -*gs-closed.

Example 3.21: In example (3.18), the subset $\{a, b\}$ is $(1, 2)$ -*gs-closed but not $(1, 2)$ -sg-closed.

Example 3.22: In example (3.6), the subset $\{a, b\}$ is $(2, 1)$ -sg-closed but not $(2, 1)$ -*gs-closed.

Remark 3.23: The union of two (i, j) -*gs-closed sets need not be (i, j) -*gs-closed set as it can be seen from the following example.

Example 3.24: In example (3.6), $\{a\}$ and $\{b\}$ are $(2, 1)$ -*gs-closed set but their union $\{a, b\}$ is not $(2, 1)$ -*gs-closed.

Remark 3.25: The intersection of two (i, j) -*gs-closed sets need not be (i, j) -*gs-closed set as it can be seen from the following example.

Example 3.26: Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, X\}$, $\tau_2 = \{\phi, \{b, c\}, X\}$. Here $\{a, b\}$ and $\{b, c\}$ are $(1, 2)$ -*gs-closed but their intersection $\{b\}$ is not $(1, 2)$ -*gs-closed.

The following diagram summarizes the above discussions.

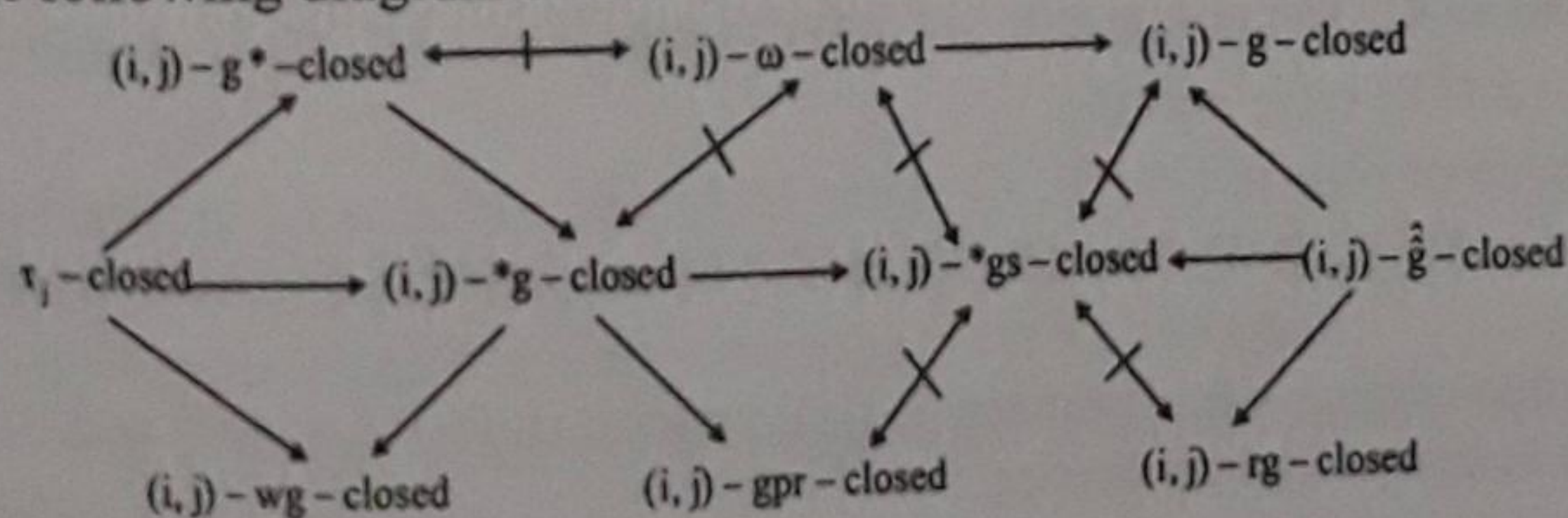


diagram (3.27)

Where $A \rightarrow B$ (resp. $A \nleftrightarrow B$) represents A implies B but converse is not necessary true (resp. A and B are independent).

Remark 3.28: $^*DS(1, 2)$ is generally not equal to $^*DS(2, 1)$ as it can be seen from the example (3.6).

Proposition 3.29: If $\tau_i \subseteq \tau_j$ in (X, τ_i, τ_j) then $^*DS(j, i) \subseteq ^*DS(i, j)$.

The converse of the above proposition is not necessarily true as seen from following example.

Example 3.30: In example (3.18), $^*DS(1, 2) \subseteq ^*DS(2, 1)$ but τ_2 is not contained in τ_1 .

Proposition 3.31: For each element x of (X, τ_1, τ_2) , $\{x\}$ is τ_i - $\hat{g}$ -closed or $\{x\}^c$ is (i, j) - *gs -closed.

Proposition 3.32: If A is (i, j) - *gs -closed then $\tau_j\text{-scl}(A) - A$ contains no non-empty τ_i - $\hat{g}$ -closed set.

Proposition 3.33: If A is (i, j) - *gs -closed set in (X, τ_1, τ_2) then A is τ_j -scl-closed if and only if $\tau_j\text{-scl}(A) - A$ is τ_i - $\hat{g}$ -closed.

Proposition 3.34: If A is an (i, j) - *gs -closed set of (X, τ_1, τ_2) such that $A \subseteq B \subseteq \tau_j\text{-scl}(A)$ then B is also an (i, j) - *gs -closed set of (X, τ_1, τ_2) .

Proposition 3.35: Let $A \subseteq Y \subseteq X$ and A is (i, j) - *gs -closed in X . Then A is (i, j) - *gs -closed relative to Y .

Proof: Proof is same as proposition (3.34).

Theorem 3.36: In a bitopological space (X, τ_1, τ_2) , $\hat{GO}(X, \tau_i) \subseteq \text{semi}F_j$ (Family of all semiclosed sets in τ_j) if and only if every subset of X is an (i, j) - *gs -closed set.

Proof: Suppose that $\hat{GO}(X, \tau_i) \subseteq \text{semi}F_j$. Let A be a subset of X such that $A \subseteq U$ where $U \in \hat{GO}(X, \tau_i)$ then $\tau_j\text{-scl}(A) \subseteq \tau_j\text{-scl}(U) = U$ and hence A is (i, j) - *gs -closed.

Conversely let every subset of X is (i, j) - *gs -closed. Let $U \in \hat{GO}(X, \tau_i)$. Since U is (i, j) - *gs -closed, we have $\tau_j\text{-scl}(U) \subseteq U$. So $U \in \text{semi}F_j$ and hence $\hat{GO}(X, \tau_i) \subseteq \text{semi}F_j$.

3. (i, j) - T_1 Spaces, (i, j) - T_1^* Spaces and (i, j) - *T_1 Spaces

In this section we introduce (i, j) - T_1 spaces, (i, j) - T_1^* spaces and (i, j) - *T_1 spaces in bitopological spaces.

Definition 4.1: A bitopological space (X, τ_1, τ_2) is said to be an (i, j) - T_1 space if every (i, j) - *gs -closed set is τ_j -closed.

Proposition 4.2: *If (X, τ_1, τ_2) is (i, j) - T_s space then it is (i) (i, j) - $T_{1/2}^\ast$ space (ii) (i, j) - $\ast gT_{1/2}^\ast$ space (iii) (i, j) - $\hat{T}_{1/2}$ space.*

The converse of the above proposition is not necessarily true as seen from following example.

Example 4.3: In example (3.6), (X, τ_1, τ_2) is $(2, 1)$ - $T_{1/2}^\ast$ space, $(2, 1)$ - $\ast gT_{1/2}^\ast$ space and $(2, 1)$ - $\hat{T}_{1/2}$ space but not $(1, 2)$ - T_s space.

Theorem 4.4: *A bitopological space (X, τ_1, τ_2) is an (i, j) - T_s space if $\{x\}$ is τ_j -open or τ_i - $\hat{g}$ -closed for each $x \in X$.*

Proof: Suppose that $\{x\}$ is not τ_i - $\hat{g}$ -closed then $\{x\}^c$ is (i, j) - $\ast$ gs-closed by proposition (3.31). Since (X, τ_1, τ_2) is an (i, j) - T_s space, $\{x\}^c$ is τ_j -closed i.e. $\{x\}$ is τ_j -open.

Proposition 4.5: *(i, j) - T_s space and (i, j) - $T_{1/2}$ space are independent.*

Definition 4.6: A bitopological space (X, τ_1, τ_2) is said to be strongly pairwise T_s -space if it is both $(1, 2)$ - T_s space and $(2, 1)$ - T_s space.

Proposition 4.7: *If (X, τ_1, τ_2) is strongly pairwise T_s -space then it is strongly pairwise $T_{1/2}^\ast$ -space (resp. strongly pairwise $\ast gT_{1/2}^\ast$ -space).*

Definition 4.8: A bitopological space (X, τ_1, τ_2) is said to be an (i, j) - $T_s^\ast$ space if every (i, j) - $\ast$ gs-closed set is τ_j -semiclosed.

Proposition 4.9: *Every (i, j) - T_s space is (i, j) - $T_s^\ast$ space.*

The converse of the above proposition is not necessarily true as seen from following example.

Example 4.10: In example (3.16), (X, τ_1, τ_2) is $(2, 1)$ - $T_s^\ast$ space but not $(2, 1)$ - T_s space.

Remark 4.11: (i, j) - $T_s^\ast$ space is not necessarily (i, j) - $T_{1/2}$ space as it can be seen from the following example.

Example 4.12: In example (3.7), (X, τ_1, τ_2) is $(1, 2)$ - $T_s^\ast$ space but not $(1, 2)$ - $T_{1/2}$ space.

Definition 4.13: A bitopological space (X, τ_1, τ_2) is said to be an (i, j) - $\ast T_s$ space if every (i, j) - $\ast$ gs-closed set is (i, j) - $\ast$ g-closed.

Proposition 4.14: *Every (i, j) - T_s space is (i, j) - $\ast T_s$ space.*

The converse of the above proposition is not necessarily true as seen from following example.

Example 4.15: In example (3.6), (X, τ_1, τ_2) is $(2, 1)$ - $\ast T_s$ space but not $(2, 1)$ - T_s space.

Remark 4.16: (X, τ_1, τ_2) is not generally $(1, 2)$ - T_s space even if both (X, τ_1) and (X, τ_2) are T_s -space as it can be seen from the following example.

Example 4.17: Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$. Here (X, τ_1) and (X, τ_2) both are T_s -space but (X, τ_1, τ_2) is not $(1, 2)$ - T_s space.

Theorem 4.18: A bitopological space (X, τ_1, τ_2) is an (i, j) - T_s space if and only if it is both (i, j) - *T_s space and (i, j) - $^*gT_{1/2}$ space.

Theorem 4.19: A bitopological space (X, τ_1, τ_2) is (i, j) - T_s space if $\{x\}$ is τ_j -open or τ_i - $\hat{g}$ -closed.

Proof: Suppose that $\{x\}$ is not τ_i - $\hat{g}$ -closed then $\{x\}^c$ is (i, j) - *gs -closed by proposition (3.31). Since (X, τ_1, τ_2) is (i, j) - T_s space, $\{x\}^c$ is τ_j -closed i. e. $\{x\}$ is τ_j -open.

The following diagram summarizes the above discussions.

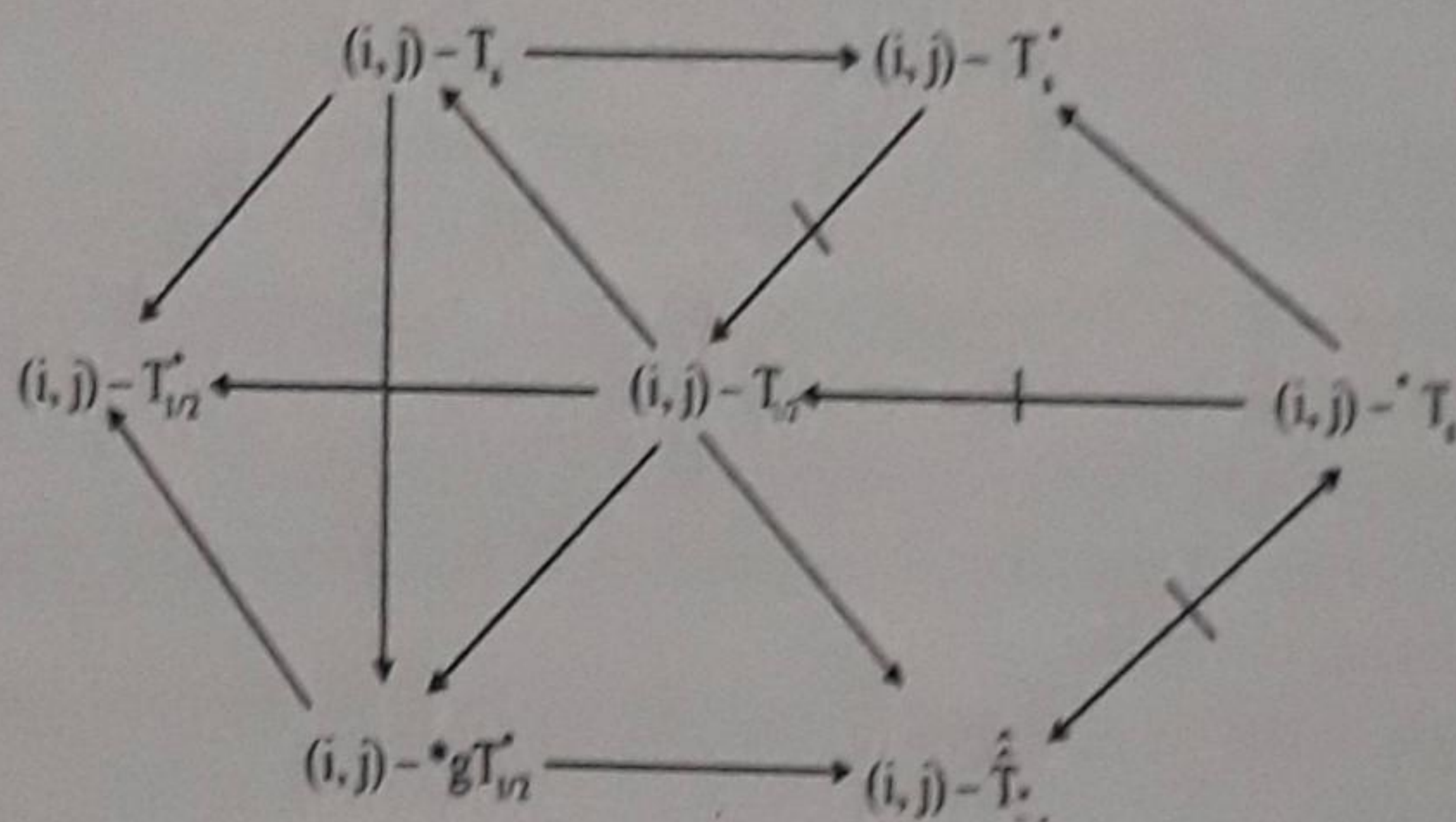


Diagram (4.20)

4. *gs -Continuous maps in Bitopological Spaces

In this section we introduce *gs -continuous maps and then discuss its properties.

Definition 5.1: A map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called $^*DS(i, j)$ - σ_k -continuous if the inverse image of every σ_k -closed set is an (i, j) - *gs -closed set.

Proposition 5.2: If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is (i) τ_j - σ_k -continuous (ii) $D^\ast(i, j)$ - σ_k -continuous (iii) $\ast D(i, j)$ - σ_k -continuous (iv) $\hat{D}(i, j)$ - σ_k -continuous then it is $\ast DS(i, j)$ - σ_k -continuous.

However the reverse implications of the above proposition are not true in general as seen from the following examples.

Example 5.3: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{a, c\}, X\}$, $\tau_2 = \{\phi, \{a, b\}, X\}$, $\sigma_1 = \{\phi, \{a\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{a, b\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\ast DS(1, 2)$ - σ_2 -continuous but not τ_1 - σ_2 -continuous.

Example 5.4: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$, $\sigma_1 = \{\phi, \{b\}, Y\}$, $\sigma_2 = \{\phi, \{c\}, \{b, c\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\ast DS(1, 2)$ - σ_2 -continuous but not $D^\ast(i, j)$ - σ_2 -continuous.

Example 5.5: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$, $\sigma_1 = \{\phi, \{b\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{a, b\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\ast DS(2, 1)$ - σ_2 -continuous but not $\ast D(2, 1)$ - σ_2 -continuous.

Example 5.6: In example (5.5), f is $\ast DS(2, 1)$ - σ_2 -continuous but not $\hat{D}(2, 1)$ - σ_2 -continuous.

Remark 5.7: $\ast DS(i, j)$ - σ_k -continuous map is independent from (i) $D(i, j)$ - σ_k -continuous (ii) $C(i, j)$ - σ_k -continuous (iii) $D_r(i, j)$ - σ_k -continuous (iv) $\zeta(i, j)$ - σ_k -continuous (v) $W(i, j)$ - σ_k -continuous as it can be seen from the following examples.

Example 5.8: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$, $\tau_2 = \{\phi, \{a\}, X\}$, $\sigma_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, Y\}$, $\sigma_2 = \{\phi, \{a, b\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\ast DS(1, 2)$ - σ_2 -continuous but not $D(1, 2)$ - σ_2 -continuous.

Example 5.9: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b, c\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{a, b\}, X\}$, $\sigma_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $D(1, 2)$ - σ_2 -continuous but not $\ast DS(1, 2)$ - σ_2 -continuous.

Example 5.10: In example (5.8), f is $\ast DS(1, 2)$ - σ_2 -continuous but not $C(2, 1)$ - σ_2 -continuous.

Example 5.11: In example (5.9), f is $C(1, 2)$ - σ_2 -continuous but not $*DS(1, 2)$ - σ_2 -continuous.

Example 5.12: In example (5.8), f is $*DS(1, 2)$ - σ_2 -continuous but not $D_t(2, 1)$ - σ_2 -continuous.

Example 5.13: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$, $\sigma_1 = \{\phi, \{b\}, \{b, c\}, Y\}$, $\sigma_2 = \{\phi, \{c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $D_t(1, 2)$ - σ_2 -continuous but not $*DS(1, 2)$ - σ_2 -continuous.

Example 5.14: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\tau_2 = \{\phi, \{a, b\}, X\}$, $\sigma_1 = \{\phi, \{b\}, \{a, b\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{c\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\zeta(1, 2)$ - σ_2 -continuous but not $*DS(1, 2)$ - σ_2 -continuous.

Example 5.15: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$, $\sigma_1 = \{\phi, \{b, c\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $*DS(2, 1)$ - σ_1 -continuous but not $\zeta(2, 1)$ - σ_1 -continuous.

Example 5.16: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\tau_2 = \{\phi, \{a, b\}, X\}$, $\sigma_1 = \{\phi, \{b, c\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $W(1, 2)$ - σ_1 -continuous but not $*DS(1, 2)$ - σ_1 -continuous.

Example 5.17: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$, $\tau_2 = \{\phi, \{a\}, X\}$, $\sigma_1 = \{\phi, \{a\}, Y\}$, $\sigma_2 = \{\phi, \{b\}, \{c\}, \{b, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $*DS(2, 1)$ - σ_2 -continuous but not $W(2, 1)$ - σ_2 -continuous.

(i) If (X, τ_1, τ_2) is an (i, j) - T_s space then f is τ_j - σ_k -continuous if and only if it is $*DS(i, j)$ - σ_k -continuous.

(ii) If (X, τ_1, τ_2) is an (i, j) - T_s space then f is (a) $D^*(i, j)$ - σ_k -continuous (b) $*D(i, j)$ - σ_k continuous (c) $\hat{D}(i, j)$ - σ_k -continuous if and only if it is $*DS(i, j)$ - σ_k -continuous.

Definition 5.20: A map. $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called $*DS(i, j)$ - σ_k -irresolute if the inverse image of every σ_k - $*gs$ -closed set in Y is (i, j) - $*gs$ -closed set in X .

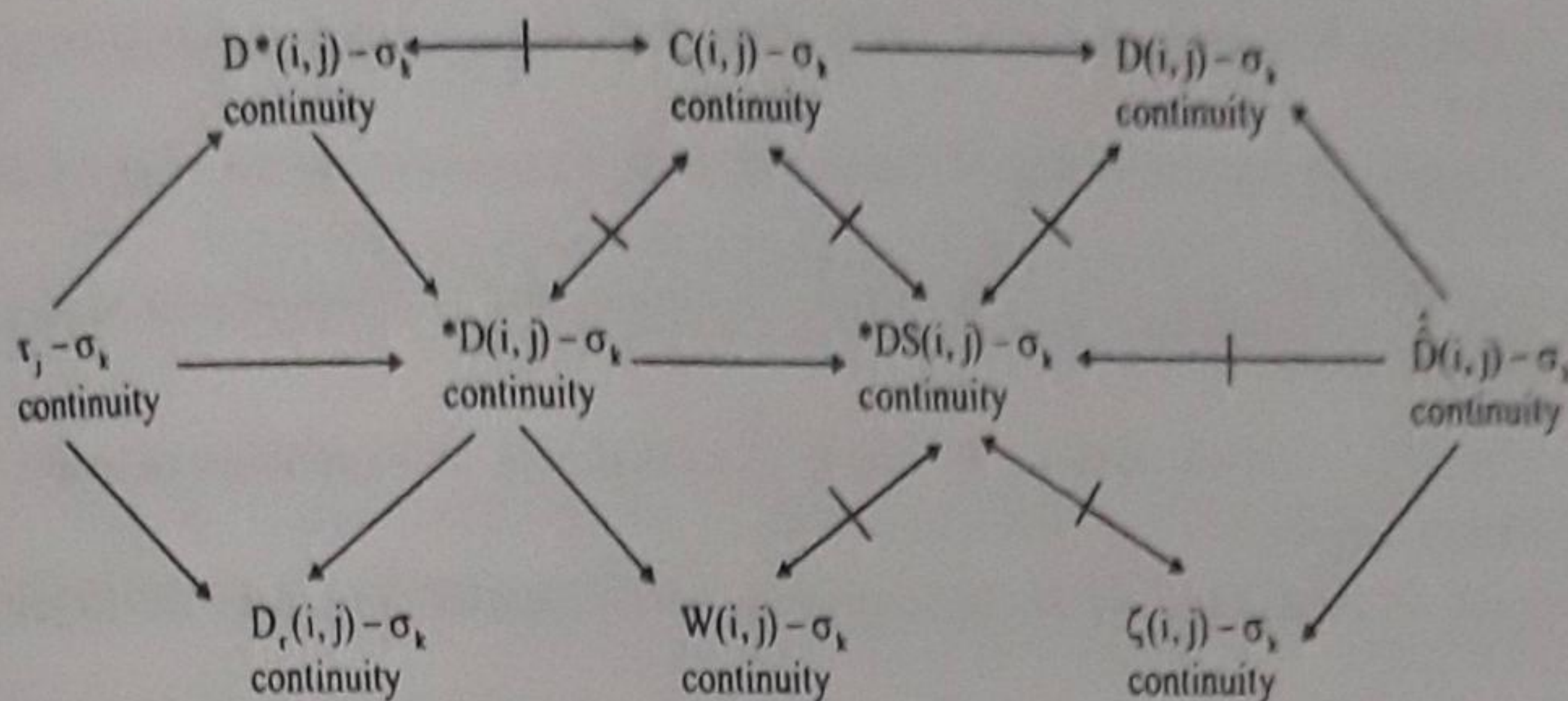


Diagram (5.18)

Proposition 5.21: If $f: (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $*DS(i, j)-\sigma_k$ -irresolute then it is $*DS(i, j)-\sigma_k$ -continuous.

However the reverse implication of the above proposition is not true in general as seen from the following example.

Example 5.22: Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b, c\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{a, b\}, X\}$, $\sigma_1 = \{\phi, \{a\}, \{a, b\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, Y\}$. Define $f: (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping, then f is $*DS(1, 2)-\sigma_2$ -continuous but not $*DS(1, 2)-\sigma_2$ -irresolute.

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