

Fuzzified Analysis of Deteriorating Inventory Model with Decreasing Demand and Changing Holding Cost

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Abstract: This paper intends to analyze an inventory model for perishable items with decreasing demand and changing holding cost in fuzzy environment by using fuzzy paradigm in order to obtain more realistic performance measure in the form of optimal total cost of the system. A non-linear equation has been developed and solved by MATHEMATICA to provide optimal total cost of the model to compare the same result obtained in crisp environment. A sensitivity analysis has also been carried out to demonstrate the use of the model under consideration.

Keywords: Cost Optimization, Inventory Control, Signed Distance Method, Fuzzy Paradigm.

1. Introduction

Inventory models with deteriorating items with their inherent characteristics have been reported by eminent researchers, for example, Raafat¹, Wee², Goyal and Giri³ and Li et al⁴. For the first time in literature the inventory model was given by Harris⁵, later it was generalized by Wilson⁶. Whitin⁷ and Ghare and Schrader⁸ presented their observations connected with deteriorating items with various distribution of time. Dave and Patel⁹ were the first who developed the inventory model on perishable items with linearly magnify demand with no scarcity. Various authors have contributed significantly in this direction and some may be referred to as Chung and Ting¹⁰, Wee¹¹, Mishra et al.¹², Mishra and Mishra¹³ and Mishra¹⁴.

Fuzzy inventory models with various characterized properties were developed and discussed by eminent researchers engaged in the fields whose contributions are cited as Abad¹⁵⁻¹⁶, Liu and Liu¹⁷, Lengari¹⁸, Mishra and Mishra¹⁹⁻²⁰, Mishra and Singh²¹⁻²², Pathak and Sarkar²³⁻²⁴, Prasath and Seshiah²⁵, Singh and Pattanayak²⁶, Mishra et al.²⁷, Kozarevic and Puska²⁸.

Zimmerman²⁹ classified the various types of uncertainties in two forms- stochastic uncertainties and fuzziness. Whenever, the process of a series of tasks including mathematical modeling, optimization, computing; expert and control systems is developed and carried out under fuzziness or fuzzy environment, it is defined as fuzzy paradigm (FP). Fuzzy paradigm in some part or as a whole may be used to analyze the model for its optimum performance measures in fuzzy environment. Of late, Dash et al.³³ has suggested an inventory model for perishable items with digressive demand as exponential function and time-varying holding cost in crisp environment.

In the present paper, the model suggested by Dash et al.³⁰ is further subjected to investigate by using FP in order to realize more realistic results with increased computational efficiency of the model. The performance measures particularly optimal total cost of the model have been computed in both of environments of crisp and fuzziness, and finally subjected to the comparison. A system of non-linear equation has been developed and its computational solution has been obtained using MATHEMETICA. A sensitivity analysis has been also carried out to test the model under consistent variation of various parameters involved in the model. The manuscript has been divided in various sections such as introduction, assumptions and notations; mathematical formulation of the model; model development and its solution in fuzzy environment; numerical computing and sensitivity analysis; and conclusion.

2. Assumptions Notations

The following assumptions and notations have been used in this manuscript for the development of the model.

Assumptions:

- (i) The inventory system is based on the single homogeneous item.
- (ii) Demand rate is exponential with respect to time and deterministic.
- (iii) Item perishes at constant rate.
- (iv) Time horizon is finite.
- (v) Lead time is considered as zero.
- (vi) There is no shortage in the system.

Notations:

- (i) A_0 is per order ordering cost.
- (ii) $I(t)$ is level of inventory at time t , $0 \leq t \leq T$.
- (iii) $D(t)$ is demand rate following exponential distribution where $D(t) = Ke^{-\gamma t}$, $K > 0$, $K \gg \gamma$ are constants, K is constant demand rate and γ the demand rate change.
- (iv) $\theta(t)$ is perishable rate of an item as constant where $\theta(t) = \theta$ ($0 < \theta < 1$) and $0 < \gamma < \theta$.
- (v) $h(t)$ is holding cost per unit time which is time dependent where $h(t) = h + \alpha t$, $h > 0$ and $\alpha > 0$.
- (vi) C_d is cost of per perishable unit.
- (viii) T is length of the ordering cycle.
- (ix) I_0 is economic order quantity.
- (x) TAC is total average cost per unit time.

3. Mathematical Formulation of the Model

According to Dash et.al³⁰, since the inventory is reduced during the time interval $[0, T]$ due to demand rate and the deterioration rate, therefore the inventory model for deteriorating items with declining demand rate is represented by the following differential equation as,

$$(3.1) \quad \frac{dI(t)}{dt} + \theta(t)I(t) = -D(t), \quad 0 \leq t \leq T,$$

where $\theta(t) = \theta$ and $D(t) = Ke^{-\gamma t}$.

The solution of the above differential equation (3.1) with the boundary condition $I(t) = I_0$ is given by

$$(3.2) \quad I(t) = \frac{K}{(\theta - \gamma)} \left[e^{(\theta - \gamma)T - \theta t} - e^{-\gamma t} \right], \quad 0 \leq t \leq T.$$

The preparatory order quantity is obtained with the boundary condition $I(0) = I_0$ for $t = 0$ in equation (3.2) as

$$(3.3) \quad I_0 = I(0) = \frac{K}{(\theta - \gamma)} \left[e^{(\theta - \gamma)T} - 1 \right].$$

During the period of cycle $[0, T]$, the total demand is given by

$$\int_0^T D(t) dt = \int_0^T K e^{-\gamma t} dt = \frac{K}{\gamma} [1 - e^{-\gamma T}].$$

The number of deteriorated units of the inventory item is

$$I_0 - \int_0^T D(t) dt = \frac{K}{(\theta - \gamma)} \left[e^{(\theta - \gamma)T} \right] + \frac{K}{\gamma} [e^{-\gamma T} - 1]$$

Thus the deteriorating cost (DC) for the period of cycle $[0, T]$ is given by

$$(3.4) \quad \begin{aligned} DC &= C_d \times \text{number of deteriorating units} \\ &= C_d \left[\frac{K}{(\theta - \gamma)} \left[e^{(\theta - \gamma)T} - 1 \right] + \frac{K}{\gamma} [e^{-\gamma T} - 1] \right] \\ &= C_d K e^{-\gamma T} \left[\frac{1}{(\theta - \gamma)} \left[e^{\theta T} - e^{\gamma T} \right] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \end{aligned}$$

The total inventory holding cost (IHC) for the period of cycle $[0, T]$ is given by

$$(3.5) \quad \begin{aligned} IHC &= \int_0^T (h + \alpha t) I(t) dt \\ &= \int_0^T (h + \alpha t) \frac{K}{(\theta - \gamma)} \left[e^{(\theta - \gamma)T - \theta t} - e^{-\gamma t} \right] dt \\ &= \frac{K e^{-\gamma T}}{\theta \gamma (\theta - \gamma)} \left[(h + \alpha T)(\theta - \gamma) - h(\theta e^{\gamma T} - \gamma e^{\theta T}) \right] \\ &\quad + \frac{\alpha}{\theta \gamma} \left[(\theta^2 - \gamma^2) - (\theta^2 e^{\gamma T} - \gamma^2 e^{\theta T}) \right]. \end{aligned}$$

Thus the total variable cost (TVC) is given by

$$TVC = OC + DC + IHC$$

Thus, (TVC/T) is given by,

$$(3.6) \quad \begin{aligned} TVC/T = & \frac{A_0}{T} + \frac{C_d K e^{-\gamma T}}{T} \left[\frac{1}{(\theta - \gamma)} [e^{\theta T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\ & + \frac{K e^{-\gamma T}}{\theta \gamma (\theta - \gamma) T} \left[\{ (h + \alpha T)(\theta - \gamma) - h(\theta e^{\gamma T} - \gamma e^{\theta T}) \} \right. \\ & \left. + \frac{\alpha}{\theta \gamma} \{ (\theta^2 - \gamma^2) - (\theta^2 e^{\gamma T} - \gamma^2 e^{\theta T}) \} \right] . \end{aligned}$$

Here, we are basically interested in finding the minimum variable cost per unit of time. Therefore, the necessary and sufficient conditions for the minimization of (TVC/T) for the given value of T are respectively given by

$$\frac{\partial(TVC/T)}{\partial T} = 0 \text{ and } \frac{\partial^2(TVC/T)}{\partial T^2} > 0$$

Now the solution of the equation $\frac{\partial(TVC/T)}{\partial T} = 0$ is given by

$$(3.7) \quad \begin{aligned} & \frac{K e^{-\gamma T}}{\theta^2 \gamma T (\theta - \gamma)} \left[\alpha \theta (\theta - \gamma) - h \theta^2 \gamma (e^{\gamma T} - e^{\theta T}) \alpha \theta (\gamma e^{\gamma T} - \theta e^{\theta T}) \right. \\ & \left. - \gamma \theta (\theta - \gamma) (h + \alpha T) + h \theta \gamma (\theta e^{\gamma T} - \gamma e^{\theta T}) - \alpha (\theta^2 - \gamma^2 - \theta^2 e^{\gamma T} + \gamma^2 e^{\theta T}) \right] \\ & + \frac{C_d K e^{-\gamma T}}{(\theta - \gamma) T} \left[\theta e^{\theta T} - \gamma e^{\gamma T} - \gamma (e^{\theta T} - e^{-\gamma T}) - \theta + \gamma \right] - \frac{A_0}{T} = 0 . \end{aligned}$$

For (TVC/T) to be minimum, we should have $\frac{\partial^2(TVC/T)}{\partial T^2} > 0$ and we have

$$\frac{\partial^2(TVC/T)}{\partial T^2} =$$

$$\begin{aligned}
& \frac{Ke^{-\gamma T}}{T^2} [\theta(\theta - \gamma)(h\gamma^2 T + \alpha T^2 \gamma^2 - 2\alpha\gamma T)\theta^2 \gamma(e^{\gamma T} - e^{\theta T})(2\gamma h T - \alpha T + 2h) \\
& + \theta(\gamma e^{\theta T} - \theta e^{\gamma T})(\gamma T - 2\alpha + 2h\gamma) + \alpha(\gamma T + 2)(\theta^2 - \gamma^2 - \theta^2 e^{\gamma T} + \gamma^2 e^{\theta T}) \\
& - hT\theta^2 \gamma(\gamma e^{\gamma T} - \theta e^{\theta T}) + 2\theta\gamma(\theta - \gamma)(h + \alpha T)] + \frac{2A_0}{T^2} \\
& + \frac{C_d Ke^{-\gamma T}}{(\theta - \gamma)T^2} [(\theta - \gamma)[(\theta - \gamma)Te^{\theta T} + \gamma T + 2] \\
& - 2\gamma(e^{\gamma T} - e^{\theta T}) - 2\gamma^2 Te^{-\gamma T} - 2\theta e^{\theta T} + 2\gamma e^{\gamma T}].
\end{aligned}$$

As we see from the numerical study that $\frac{\partial^2(TVC/T)}{\partial T^2} > 0$ for the optimal value of T obtained from equation (3.7), therefore the equation (3.6) has unique optimal solution.

4. Model Development and its Solution in Fuzzy Environment

Now, we fuzzify the parameters involved as under:

Let $\tilde{h} = (h_1, h_2, h_3, h_4)$, $\tilde{C}_d = (C_{d1}, C_{d2}, C_{d3}, C_{d4})$, $\tilde{\theta} = (\theta_1, \theta_2, \theta_3, \theta_4)$ be the trapezoidal fuzzy numbers. Then, we have fuzzified TVC as,

$$\begin{aligned}
T\tilde{V}C/T &= \frac{A_0}{T} + \frac{C_d Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta - \gamma)} [e^{\theta T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
&+ \frac{Ke^{-\gamma T}}{\tilde{\theta}\gamma(\tilde{\theta} - \gamma)} [(\tilde{h} + \alpha T)(\tilde{\theta} - \gamma) - \tilde{h}(\tilde{\theta} e^{\gamma T} - \gamma e^{\tilde{\theta} T})] \\
&+ \frac{\alpha}{\tilde{\theta}\gamma} [(\tilde{\theta}^2 - \gamma^2) - (\tilde{\theta}^2 e^{\gamma T} - \gamma^2 e^{\tilde{\theta} T})] \\
T\tilde{V}C/T &= \frac{A_0}{T} + \frac{(C_{d1}, C_{d2}, C_{d3}, C_{d4})Ke^{-\gamma T}}{T} \\
&\times \left[\frac{1}{\{(\theta_1, \theta_2, \theta_3, \theta_4) - \gamma\}} [e^{(\theta_1, \theta_2, \theta_3, \theta_4)T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right]
\end{aligned}$$

$$\begin{aligned}
& + \frac{Ke^{-\gamma T}}{(\theta_1, \theta_2, \theta_3, \theta_4)\gamma\{(\theta_1, \theta_2, \theta_3, \theta_4) - \gamma\}} \\
& \times \left[\{(h_1, h_2, h_3, h_4) + \alpha T\}\{(\theta_1, \theta_2, \theta_3, \theta_4) - \gamma\} \right. \\
& \quad \left. - (h_1, h_2, h_3, h_4)\{(\theta_1, \theta_2, \theta_3, \theta_4)e^{\gamma T} - \gamma e^{(\theta_1, \theta_2, \theta_3, \theta_4)T}\} \right] \\
& + \frac{\alpha}{(\theta_1, \theta_2, \theta_3, \theta_4)\gamma} \left[\{(\theta_1^2, \theta_2^2, \theta_3^2, \theta_4^2) - \gamma^2\} \right. \\
& \quad \left. - \{(\theta_1^2, \theta_2^2, \theta_3^2, \theta_4^2)e^{\gamma T} - \gamma^2 e^{(\theta_1, \theta_2, \theta_3, \theta_4)T}\} \right] \\
& \tilde{TV}C/T = (W, X, Y, Z)
\end{aligned}$$

where,

$$\begin{aligned}
W &= \frac{A_0}{T} + \frac{C_{d1}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_1 - \gamma)} [e^{\theta_1 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
&+ \frac{Ke^{-\gamma T}}{\theta_1 \gamma (\theta_1 - \gamma)} [(h_1 + \alpha T)(\theta_1 - \gamma) - h_1(\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T})] \\
&+ \frac{\alpha}{\theta_1 \gamma} [(\theta_1^2 - \gamma^2) - (\theta_1^2 e^{\gamma T} - \gamma^2 e^{\theta_1 T})] \\
X &= \frac{A_0}{T} + \frac{C_{d2}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_2 - \gamma)} [e^{\theta_2 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
&+ \frac{Ke^{-\gamma T}}{\theta_2 \gamma (\theta_2 - \gamma)} [(h_2 + \alpha T)(\theta_2 - \gamma) - h_2(\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T})] \\
&+ \frac{\alpha}{\theta_2 \gamma} [(\theta_2^2 - \gamma^2) - (\theta_2^2 e^{\gamma T} - \gamma^2 e^{\theta_2 T})] \\
Y &= \frac{A_0}{T} + \frac{C_{d3}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_3 - \gamma)} [e^{\theta_3 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
&+ \frac{Ke^{-\gamma T}}{\theta_3 \gamma (\theta_3 - \gamma)} [(h_3 + \alpha T)(\theta_3 - \gamma) - h_3(\theta_3 e^{\gamma T} - \gamma e^{\theta_3 T})]
\end{aligned}$$

$$\begin{aligned}
& + \frac{\alpha}{\theta_3 \gamma} [(\theta_3^2 - \gamma^2) - (\theta_3^2 e^{\gamma T} - \gamma^2 e^{\theta_3 T})] \\
Z = & \frac{A_0}{T} + \frac{C_{d4} K e^{-\gamma T}}{T} \left[\frac{1}{(\theta_4 - \gamma)} [e^{\theta_4 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
& + \frac{K e^{-\gamma T}}{\theta_4 \gamma (\theta_4 - \gamma)} [(h_4 + \alpha T)(\theta_4 - \gamma) - h_4(\theta_4 e^{\gamma T} - \gamma e^{\theta_4 T})] \\
& + \frac{\alpha}{\theta_4 \gamma} [(\theta_4^2 - \gamma^2) - (\theta_4^2 e^{\gamma T} - \gamma^2 e^{\theta_4 T})].
\end{aligned}$$

The α -Cuts, $C_L(\alpha)$ and $C_R(\alpha)$ of trapezoidal fuzzy number $(\tilde{TV}C/T)$ are given by,

$$\begin{aligned}
C_L(\alpha) = & W + (X - W)\alpha \\
= & \frac{A_0}{T} + \frac{C_{d1} K e^{-\gamma T}}{T} \left[\frac{1}{(\theta_1 - \gamma)} [e^{\theta_1 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
& + \frac{K e^{-\gamma T}}{\theta_1 \gamma (\theta_1 - \gamma)} [(h_1 + \alpha T)(\theta_1 - \gamma) - h_1(\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T})] \\
& + \frac{\alpha}{\theta_1 \gamma} [(\theta_1^2 - \gamma^2) - (\theta_1^2 e^{\gamma T} - \gamma^2 e^{\theta_1 T})] \\
& + \left[\frac{C_{d2} K e^{-\gamma T}}{T} \left[\frac{1}{(\theta_2 - \gamma)} [e^{\theta_2 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \right. \\
& \left. - \frac{C_{d1} K e^{-\gamma T}}{T} \left[\frac{1}{(\theta_1 - \gamma)} [e^{\theta_1 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \right] \\
& + \frac{K e^{-\gamma T}}{\theta_2 \gamma (\theta_2 - \gamma)} [(h_2 + \alpha T)(\theta_2 - \gamma) - h_2(\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T})]
\end{aligned}$$

$$\begin{aligned}
& -\frac{\alpha}{\theta_2\gamma}[(\theta_2^2 - \gamma^2) - (\theta_2^2 e^{\gamma T} - \gamma^2 e^{\theta_2 T})] \\
& -\frac{\alpha}{\theta_1\gamma}[(\theta_1^2 - \gamma^2) - (\theta_1^2 e^{\gamma T} - \gamma^2 e^{\theta_1 T})] \Big] \alpha
\end{aligned}$$

and

$$\begin{aligned}
C_R(\alpha) &= Z - (Z - Y)\alpha \\
&= \frac{A_0}{T} + \frac{C_{d4}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_4 - \gamma)} [e^{\theta_4 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
&\quad + \frac{Ke^{-\gamma T}}{\theta_4\gamma(\theta_4 - \gamma)} [(h_4 + \alpha T)(\theta_4 - \gamma) - h_4(\theta_4 e^{\gamma T} - \gamma e^{\theta_4 T})] \\
&\quad + \frac{\alpha}{\theta_4\gamma} [(\theta_4^2 - \gamma^2) - (\theta_4^2 e^{\gamma T} - \gamma^2 e^{\theta_4 T})] \\
&\quad - \left[\frac{C_{d4}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_4 - \gamma)} [e^{\theta_4 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \right. \\
&\quad \left. - \frac{C_{d3}Ke^{-\gamma T}}{T} \left[\frac{1}{(\theta_3 - \gamma)} [e^{\theta_3 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \right. \\
&\quad \left. + \frac{Ke^{-\gamma T}}{\theta_4\gamma(\theta_4 - \gamma)} [(h_4 + \alpha T)(\theta_4 - \gamma) - h_4(\theta_4 e^{\gamma T} - \gamma e^{\theta_4 T})] \right. \\
&\quad \left. - \frac{Ke^{-\gamma T}}{\theta_3\gamma(\theta_3 - \gamma)} [(h_3 + \alpha T)(\theta_3 - \gamma) - h_3(\theta_3 e^{\gamma T} - \gamma e^{\theta_3 T})] \right. \\
&\quad \left. + \frac{\alpha}{\theta_4\gamma} [(\theta_4^2 - \gamma^2) - (\theta_4^2 e^{\gamma T} - \gamma^2 e^{\theta_4 T})] \right. \\
&\quad \left. - \frac{\alpha}{\theta_3\gamma} [(\theta_3^2 - \gamma^2) - (\theta_3^2 e^{\gamma T} - \gamma^2 e^{\theta_3 T})] \right] \alpha
\end{aligned}$$

The defuzzified value of the fuzzy number ($T\tilde{V}C/T$), using signed distance method is given by,

$$\begin{aligned}
 TVC/T &= \frac{1}{2} \int_0^1 [C_L(\alpha) + C_R(\alpha)] d\alpha \\
 &= \frac{A_0}{T} + \frac{C_{d1}Ke^{-\gamma T}}{2T} \left[\frac{1}{(\theta_1 - \gamma)} [e^{\theta_1 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
 &\quad + \frac{Ke^{-\gamma T}}{2\theta_1\gamma(\theta_1 - \gamma)} \left[(h_1 + \frac{T}{2})(\theta_1 - \gamma) - h_1(\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T}) \right] \\
 &\quad + \frac{1}{4\theta_1\gamma} [(\theta_1^2 - \gamma^2) - (\theta_1^2 e^{\gamma T} - \gamma^2 e^{\theta_1 T})] \\
 &\quad - \frac{C_{d2}Ke^{-\gamma T}}{2T} \left[\frac{1}{(\theta_2 - \gamma)} [e^{\theta_2 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
 &\quad + \frac{C_{d1}Ke^{-\gamma T}}{2T} \left[\frac{1}{(\theta_1 - \gamma)} [e^{\theta_1 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
 &\quad - \frac{Ke^{-\gamma T}}{\theta_2\gamma} \left(\frac{h_2}{2} + \frac{T}{4} \right) + \frac{Ke^{-\gamma T}}{\theta_1\gamma} \left(\frac{h_1}{2} + \frac{T}{4} \right) \\
 &\quad - \frac{Ke^{-\gamma T}h_1}{2\theta_1\gamma(\theta_1 - \gamma)} [(\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T})] \\
 &\quad + \frac{1}{6\theta_2\gamma} [(\theta_2^2 - \gamma^2) - (\theta_2^2 e^{\gamma T} - \gamma^2 e^{\theta_2 T})] \\
 &\quad - \frac{1}{6\theta_1\gamma} [(\theta_1^2 - \gamma^2) - (\theta_1^2 e^{\gamma T} - \gamma^2 e^{\theta_1 T})] + \frac{C_{d4}Ke^{-\gamma T}}{2T}
 \end{aligned}$$

$$\begin{aligned}
& \left[\frac{1}{(\theta_4 - \gamma)} [e^{\theta_4 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] + \frac{Ke^{-\gamma T}}{2\theta_4 \gamma (\theta_4 - \gamma)} \\
& \left[\left(h_4 + \frac{T}{2} \right) (\theta_4 - \gamma) - h_4 (\theta_4 e^{\gamma T} - \gamma e^{\theta_4 T}) \right] \\
& - \frac{C_{d4} Ke^{-\gamma T}}{2T} \left[\frac{1}{(\theta_4 - \gamma)} [e^{\theta_4 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
& + \frac{C_{d3} Ke^{-\gamma T}}{2T} \left[\frac{1}{(\theta_3 - \gamma)} [e^{\theta_3 T} - e^{\gamma T}] + \frac{1}{\gamma} [1 - e^{-\gamma T}] \right] \\
& - \frac{Ke^{-\gamma T}}{2\theta_4 \gamma} \left(\frac{h_4}{2} + \frac{T}{4} \right) + \frac{Ke^{-\gamma T} h_4}{\theta_4 \gamma (\theta_4 - \gamma)} [(\theta_4 e^{\gamma T} - \gamma e^{\theta_4 T})] \\
& + \frac{Ke^{-\gamma T}}{2\theta_3 \gamma} \left(\frac{h_3}{2} + \frac{T}{4} \right) - \frac{Ke^{-\gamma T} h_3}{\theta_3 \gamma (\theta_3 - \gamma)} [(\theta_3 e^{\gamma T} - \gamma e^{\theta_3 T})] \\
& + \frac{1}{6\theta_4 \gamma} [(\theta_4^2 - \gamma^2) - (\theta_4^2 e^{\gamma T} - \gamma^2 e^{\theta_4 T})] \\
& - \frac{1}{6\theta_3 \gamma} [(\theta_3^2 - \gamma^2) - (\theta_3^2 e^{\gamma T} - \gamma^2 e^{\theta_3 T})].
\end{aligned}$$

The optimal value of T is obtained using the method of maxima-minima by solving the equation $\frac{\partial TVC_{ds}(T)}{\partial T} = 0$ for T with the sufficient condition $\frac{\partial^2 TVC_{ds}(T)}{\partial T^2} > 0$.

Thus, $\frac{\partial TVC_{ds}(T)}{\partial T} =$

$$\begin{aligned}
& \frac{C_{d1} K}{2T^2} \left[T e^{T(\theta_1 - \gamma)} - \frac{2e^{-\gamma T}}{(\theta_1 - \gamma)} (e^{\theta_1 T} - e^{\gamma T}) \right] \\
& + \frac{e^{-\gamma T}}{2\gamma T^2} [2\gamma T (2e^{-\gamma T} - 1) - (1 - e^{-\gamma T})]
\end{aligned}$$

$$\begin{aligned}
& + \frac{K e^{-\gamma T}}{4\gamma\theta_1} \left(1 - \gamma \left(h + \frac{T}{2} \right) \right) - \frac{K h_1 e^{-\gamma T}}{2\gamma\theta_1(\theta_1 - \gamma)} \\
& \times \left[\theta_1 \gamma (e^{\gamma T} - e^{\theta_1 T}) + (\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T}) \right] \\
& + \theta_2 \gamma (\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T}) \frac{C_{d2} K}{2T^2} \left[T e^{T(\theta_2 - \gamma)} - \frac{2e^{-\gamma T}}{(\theta_2 - \gamma)} (e^{\theta_2 T} - e^{\gamma T}) \right] \\
& + \frac{e^{-\gamma T}}{2\gamma T^2} \left[2\gamma T (2e^{-\gamma T} - 1) - (1 - e^{-\gamma T}) \right] + \frac{K e^{-\gamma T}}{4\gamma\theta_2} \\
& \left(1 - \gamma \left(h + \frac{T}{2} \right) \right) - \frac{2e^{-\gamma T}}{2\gamma\theta_2(\theta_2 - \gamma)} \left[\theta_2 \gamma (e^{\gamma T} - e^{\theta_2 T}) \right] \\
& + (\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T}) + (\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T}) \\
& + \frac{C_{d1} K}{2T^2} \left[T e^{T(\theta_1 - \gamma)} - \frac{2e^{-\gamma T}}{(\theta_1 - \gamma)} (e^{\theta_1 T} - e^{\gamma T}) \right] + \frac{e^{-\gamma T}}{2\gamma T^2} \\
& \times \left[2\gamma T (2e^{-\gamma T} - 1) - (1 - e^{-\gamma T}) \right] + \frac{K e^{-\gamma T}}{4\gamma\theta_1} \\
& \times \left(1 - \gamma \left(h + \frac{T}{2} \right) \right) - \frac{K h_1 e^{-\gamma T}}{2\gamma\theta_1(\theta_1 - \gamma)} \left[\theta_1 \gamma (e^{\gamma T} - e^{\theta_1 T}) + (\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T}) \right] \\
& + \theta_2 \gamma (\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T}) \frac{C_{d1} K}{2T^2} \left[T e^{T(\theta_1 - \gamma)} - \frac{2e^{-\gamma T}}{(\theta_1 - \gamma)} (e^{\theta_1 T} - e^{\gamma T}) \right] \\
& + \frac{e^{-\gamma T}}{2\gamma T^2} \left[2\gamma T (2e^{-\gamma T} - 1) - (1 - e^{-\gamma T}) \right] + \frac{K e^{-\gamma T}}{4\gamma\theta_1} \\
& \times \left(1 - \gamma \left(h + \frac{T}{2} \right) \right) - \frac{K h_1 e^{-\gamma T}}{2\gamma\theta_1(\theta_1 - \gamma)} \left[\theta_1 \gamma (e^{\gamma T} - e^{\theta_1 T}) + (\theta_1 e^{\gamma T} - \gamma e^{\theta_1 T}) \right] \\
& + \theta_2 \gamma (\theta_2 e^{\gamma T} - \gamma e^{\theta_2 T}) - \frac{A_0}{T^2} = 0.
\end{aligned}$$

5. Numerical computing and Sensitivity Analysis

The numerical computing related to different results of the model is primarily become a basis for performing the sensitivity analysis of the model. The sensitivity mainly seeks to explore variations of various parameters involved in the model with respect to total optimal cost of the model as a main performance measure

Table1 shows the comparison of the total optimal cost in both environments- crisp as well as fuzzy. Tables 2-4 provide the variational study of total optimal cost with respect to rate of deterioration, total optimal cost with respect to rate of deterioration cost, total optimal cost with respect to rate of holding cost. Moreover, trend of correlation of total optimal cost with these parameters are positive as evident from tables 2-4. The parametric values for the inventory system are as follows:

Crisp Model: $A_0 = 200$ per order /unit, $h = 5$ per year/unit, $C_d = 20$ per unit per year. The solution of crisp model is $TAC = Rs\ 515.7690$, $T = 1.8643$.

Fuzzy Model: The following are the two methods for obtaining the solution of the fuzzy model.

Table 1. Comparison of Optimal Results

Model	Optimal T	Opt I	Optimal TAC
Crisp Model	1.8643	67.4336	515.7690
Fuzzy Model	1.6592	72.3235	591.5366

Table 2. Sensitivity Analysis with respect to θ

Defuzzified θ	Fuzzified parameter	T (year)	$\tilde{TAC}(t, T)$
0.005	(0.001, 0.004, 0.008, 0.012)	1.4832	512.411
0.007	(0.002, 0.006, 0.010, 0.014)	1.5530	536.572
0.009	(0.004, 0.008, 0.012, 0.016)	1.5967	577.553
0.011	(0.006, 0.010, 0.014, 0.018)	1.6592	591.566
0.013	(0.008, 0.012, 0.016, 0.020)	1.9660	611.809

Table 3. Sensitivity Analysis with respect to h

Defuzzified h	Fuzzified parameter	T (year)	$\tilde{TAC} (t, T)$
3	(1, 2, 4, 6)	1.5552	544.099
4	(1, 3, 5, 7)	1.5596	555.762
5	(2, 4, 6, 8)	1.5898	567.658
6	(3, 5, 7, 9)	1.6592	591.536
7	(4, 6, 8, 10)	1.6921	655.063

6. Conclusion

This paper presents the comparison of results between crisp and fuzzy environments to comprehensively gain the realistic spectrum of the model for effective judgment of applications. Here, fuzzy paradigm is used to handle an uncertainty in the environment of fuzziness whereas other several techniques including dynamic, heuristic and stochastic process have been used to investigate the uncertainty other than fuzziness. Through numerical computing as given in tables 1-3, various performance measures including optimal total cost of the model as main result of the model have been computed in fuzzy environment. In tables 2-3, correlations between optimal total cost and other parameters of the model have been discussed. The model will be subjected to further investigation under intuitionistic fuzzy paradigm as a future research.

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