Almost Kenmotsu Manifold Admitting Semi-Symmetric Metric Connection

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Abstract: We study almost Kenmotsu manifold admitting semi-symmetric metric connection. We proved the conditions for this manifold to be of constant curvature. Further we verify our results by giving an example.

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1. Introduction

A normal manifold with closed 1-form η and $d\varphi = 2\eta \Lambda \varphi$ called almost Kenmotsu manifold was studied by Dileo and Pastore¹. They also investigated locally symmetric almost Kenmotsu manifolds. Wang and Liu²⁻⁴ Dey and Majhi5 proved some interesting theorems in almost Kenmotsu manifolds with nullity distributions.

The notion semi-symmetric linear connection was initially studied by Friedmann and Schouten⁶ and the study was continued by Hayden⁷. Further Yano systematically studied semi-symmetric metric connection on Riemannian manifolds⁸, and the study extended to almost contact metric manifolds by several others.

Here we study almost Kenmotsu manifold M admitting semi-symmetric metric connection $\hat{\nabla}$. We give preliminaries and basic results in section 2. In Section 3, we obtain conditions for M with $\hat{\nabla}$ to be of constant curvature provided it satisfies certain semi-symmetry, Ricci-semi

symmetry conditions with respect to $\hat{\nabla}$ and flatness like curvature conditions with respect to conformal, concircular and projective curvature tensors. We constructed an example in section 4 to verify our results.

2. Preliminaries

Let $M^{2n+1}(\varphi, \xi, \eta, g)$ be an almost contact metric manifold, where φ, ξ, η and g are respectively a (1, 1) tensor field, characteristic vector field and a 1-form on M satisfying

(2.1)
$$\phi^2 Z = -Z + \eta(Z)\xi, \quad \eta(\xi) = 1.$$

From (2.1) we have rank $(\phi) = 2n$ and

$$(2.2) \eta \cdot \phi = 0, \quad \phi \xi = 0,$$

(2.3)
$$g(\phi Y, \phi Z) = g(Y, Z) - \eta(Y)\eta(Z).$$

Now, we denote by $l = R(\cdot, \xi)\xi$ and $h = \frac{1}{2}L_{\xi}\phi$, two symmetric (1, 1)-type tensors on M. The tensors l and h satisfy:

$$h\xi = 0$$
, $\operatorname{tr} h = 0$, $\operatorname{tr} \left(h\varphi\right) = 0$, $h\varphi + \varphi h = 0$.

(2.4)
$$\nabla_X \xi = -\varphi^2 X + h \varphi X ,$$

(2.5)
$$(\nabla_Y \eta) Z = g(Y, Z) - \eta(Y) \eta(Z) + g(h\varphi Y, Z),$$

$$(2.6) l - \varphi l \varphi = -2 \left(h^2 - \varphi^2 \right),$$

(2.7)
$$(\nabla_X \varphi) Y = g(\varphi X, Y) \xi - \eta(Y) \varphi X,$$

(2.8)
$$R(X,Y)\xi = \eta(X)(Y - \varphi hY) - \eta(Y)(X - \varphi hX) - (\nabla_X \varphi h)Y + (\nabla_Y \varphi h)X,$$

(2.9)
$$\nabla_{\varepsilon} h = -\varphi h^2 - \varphi - 2h - \varphi l,$$

(2.10)
$$S(X,\xi) = -2n\eta(X) + g(\operatorname{div}(\varphi h), X),$$

(2.11)
$$\operatorname{tr}(l) = -2n + \operatorname{tr} h^2 = S(\xi, \xi),$$

where $X, Y \in TM$, S is Ricci tensor, ∇ is Levi-civita connection in M respectively. Also $\nabla_{\varepsilon} \varphi = 0$.

Throughout this paper the quantities with cap are with respect to semi-symmetric metric connection $\hat{\nabla}$ and the quantity without cap are with respect to Levi-civita connection ∇ . The connections $\hat{\nabla}$ and ∇ are related by 4

$$(2.12) \qquad \hat{\nabla}_X Y = \nabla_X Y + \eta(Y) X - g(X, Y) \xi.$$

Taking $Y = \xi$ in (2.12) we have,

$$\hat{\nabla}_X \xi = -2\varphi^2 X - \varphi h X .$$

Using the definition of R and (2.12), we have

(2.14)
$$\hat{R}(V,U)Z = R(V,U)Z + 3[g(V,Z)U - g(U,Z)V]$$

$$+2\eta(Z)[\eta(U)V - \eta(V)U]$$

$$+2[g(U,Z)\eta(V) - g(V,Z)\eta(U)]\xi$$

$$+g(\varphi h U, Z)V - g(\varphi h V, Z)U$$

$$-g(V,Z)\varphi h U + g(U,Z)\varphi h V.$$

Contracting (2.14) on V, we have

(2.15)
$$\hat{S}(U,Z) = S(U,Z) - (6n-2)g(U,Z) + (4n-2)\eta(U)\eta(Z) + (2n-1)g(\varphi h U, Z).$$

Again contracting (2.15), we get

$$(2.16) \hat{r} = r - 2n(6n-1).$$

From (2.16), we have the following:

(2.17)
$$\hat{R}(V,Z)\xi = 2\eta(V)(Z - \varphi h Z) - 2\eta(Z)(V - \varphi h V) - (\nabla_V \varphi h)Z + (\nabla_Z \varphi h)V.$$

(2.18)
$$\hat{R}(V,\xi)Z = 2g(V,Z) - g(\varphi hV,Z)\xi - \eta(Z)$$
$$\times \left[2V - 3\varphi V + h^2 V - \varphi(\nabla_{\xi} h)V\right].$$

From (2.15), we derive

$$(2.19) \qquad \hat{S}(\xi, U) = -4n\eta(U) + g(div(\varphi h), U),$$

$$(2.20) \qquad \hat{S}(\xi,\xi) = -4n + \operatorname{tr}(h^2).$$

Definition 2.1: A Riemannian manifold M is said to be (i) Projectively flat if the projective curvature tensor H given by

$$(2.21) H(V,Z)U = R(V,Z)U - \frac{1}{2n} \left[S(Z,U)V - S(V,U)Z \right]$$

vanishes identically on M.

(ii) Concircularly flat if a (0,4) tensor C(V,U,W,Z) invariant under concircular transformation called the concircular curvature tensor given by

(2.22)
$$C(X,U,W,Z) = R(X,U,W,Z) - \frac{r}{2n(2n-1)}$$
$$\times \left[g(U,W)g(X,Z) - g(X,W)g(U,Z) \right]$$

vanishes. i.e. C(V, U, W, Z) = 0.

(iii) Conformally flat if the conformal curvature tensor K given by

(2.23)
$$K(V,U)Z = R(V,U)Z + \frac{r}{2n(2n-1)} [g(U,Z)V - g(V,Z)U]$$

$$-\frac{1}{2n-1}\Big[S(U,Z)V-S(V,Z)U+g(U,Z)QV-g(V,Z)QU\Big]$$

vanishes.

3. Results and Analysis

Throughout this section M^* denote (2n+1) dimensional almost Kenmotsu manifold admitting semi-symmetric metric connection $\hat{\nabla}$ and $\left\{e_i:i=1,2,.....2n+1\right\}$ denote an orthonormal basis of the tangent space at each point of M.

Lemma 3.1: If M^* is Ricci-semi-symmetric with respect to $\hat{\nabla}$ then $\operatorname{tr} h^2 = 0$.

Proof: Suppose in M^* , $(\hat{R}(U, V) \cdot \hat{S})(Z, W) = 0$ holds.

$$(3.1) \qquad \hat{S}(\hat{R}(U,V)W,Z) + \hat{S}(W,\hat{R}(V,U)Z) = 0.$$

Using (2.14), (2.15) in (3.1), and taking $U = V = \xi$, we get

(3.2)
$$S(R(V,\xi)W,\xi) + S(W,R(V,\xi)\xi) = -(4n-2)$$

$$\times [g(V,W) - \eta(V)\eta(W)] - (2n-1)g(\varphi hW,R(V,\xi)\xi)$$

$$-g(V,W)[-4n+trh^{2}] + \eta(W)[g(div(\varphi h),V)]$$

$$+g(\varphi hV,W)[-4n+trh^{2}] - \eta(V)[g(div(\varphi h),W)]$$

$$+[S(W,V) - (6n-2)g(W,V) + (4n-2)\eta(V)\eta(W)$$

$$+(2n-1)g(\varphi hV,W)] - [S(W,\varphi hV) - (6n-2)$$

$$\times g(W,\varphi hV) + (2n-1)g(hV,hW)].$$

Now, we take $W = \xi$ in (3.2), and simplify by using (2.8) and (2.10) to get, $\operatorname{tr} h^2 = 0$. **Lemma 3.2:** If M^* is

(i) Concircularly flat with respect to $\hat{\nabla}$, then

$$r = tr(h^2) + 2n(2n-3).$$

(ii) Projectivelly flat with respect to $\hat{\nabla}$, then

$$r = (4n+1)tr h^2 + 2n(2n-3).$$

(iii) φ -projectively semi-symmetric with respect to $\hat{\nabla}$, then

$$r = 2n(2n-3)+(4n+1)tr h^2$$
.

Proof: Case (i): Suppose M^* is concircularly flat with respect to $\hat{\nabla}$. Then from (2.22), we have

(3.3)
$$g(\hat{R}(U,V)W, X) = \frac{\hat{r}}{2n(2n+1)} [g(U,W)g(V,X) - g(V,W)g(U,X)].$$

Setting $V = X = \xi$, and using (2.16), (2.22) we get,

$$(3.4) -2g(\varphi U, \varphi W) + 3g(\varphi h U, W) - g(h^{2}U, W) + g(\varphi(\nabla_{\xi}h)U, W)$$
$$= \frac{r - 2n(6n - 1)}{2n(2n + 1)} [g(U, W) - \eta(U)\eta(W)].$$

Setting $U = W = e_i$, in (3.4) and then summing over $i = 1, 2, \dots, 2n + 1$, we obtain

$$(3.5) r = (2n+1)tr\left(\varphi(\nabla_{\xi}h)\right) - (2n+1)tr(h^2) + 2n(2n-3).$$

Now from (2.9), (2.11) and $tr(h\varphi) = 0$, it follows that $tr(\varphi(\nabla_{\xi}h)) = 2tr(h^2)$. Substituting this in (3.5), we get

(3.6)
$$r = tr(h^2) + 2n(2n-3).$$

Case (ii): If M^* is projectively flat, then (2.21), becomes

(3.7)
$$\hat{R}(U,V)Z = \frac{1}{2n} \left[\hat{S}(V,Z)U - \hat{S}(U,Z)V \right].$$

Taking inner product with W and setting $V = W = \xi$, and by using (2.14) and (2.20), we get

(3.8)
$$S(V,Z) = (2n-2+trh^2)g(V,Z) - (4n-2)\eta(V)\eta(Z) - (4n+1)g(\varphi h V, Z).$$

Setting $V = Z = e_i$ in (3.8) and summing over i from $i = 1, 2, \dots, 2n + 1$, we get

(3.9)
$$r = (4n+1)tr h^2 + 2n(2n-3).$$

Case (iii): Suppose M^* is φ -projectively semi-symmetric with respect to $\hat{\nabla}$ i.e., $\hat{H}o\varphi = 0$. Then

$$(3.10) \qquad \hat{H}(U,V)\varphi W - \varphi \hat{H}(U,V)W = 0,$$

which implies

(3.11)
$$\hat{R}(U,V)\varphi W - \varphi \hat{R}(U,V)W - \frac{1}{2n} \left[\hat{S}(V,\varphi W)U - \hat{S}(U,\varphi W)V + \hat{S}(V,W)\varphi U - \hat{S}(U,W)\varphi V \right] = 0.$$

Taking $V = \xi$ in (3.11) we have,

(3.12)
$$\hat{R}(U,\xi)\varphi W - \varphi \hat{R}(U,\xi)W - \frac{1}{2n} \Big[\hat{S}(\xi,\varphi W) U - \hat{S}(U,\varphi W) \xi + \hat{S}(\xi,W) \varphi U \Big] = 0.$$

By using (2.14) and (2.20) and taking inner product with ξ , we get

(3.13)
$$S(U, \varphi W) = (2n - 2 + tr h^2) g(U, \varphi W) + g(hU, W).$$

Replacing W by φW in (3.13), we have

(3.14)
$$S(U,W) = 2(n-1+trh^2)g(U,W) - (4n-2+trh^2)$$
$$\times \eta(U)\eta(W) + g(\varphi hU,W).$$

Setting $U = W = e_i$, in (3.14), summing over $i = 1, 2, \dots, 2n + 1$, we get

(3.15)
$$r = 2n(2n-3) + (4n+1)tr h^2.$$

Hence lemma (3.1) follows from case (i)-(iii). Now from Lemma 3.1 and Lemma 3.2), we state the following

Theorem 3.1: If M^* is either concircularly flat or projectively flat or φ -projectively semi-symmetric with respect to $\hat{\nabla}$, then M is of constant scalar curvature.

Theorem 3.2: The manifold M^* is conformally flat (or φ -conformally semi-symmetric) with respect to $\hat{\nabla}$ if and only if $\operatorname{tr} h^2 = 0$.

Proof: Case (i): Suppose M^* is conformally flat with respect to $\hat{\nabla}$. Then from (2.23), we have

(3.16)
$$\hat{R}(U,V)W = \frac{1}{2n-1} \Big[\hat{S}(V,W)U - \hat{S}(U,W)V + g(V,W)\hat{Q}U - g(U,W)\hat{Q}V \Big] - \frac{\hat{r}}{2n(2n-1)} \Big[g(V,W)U - g(U,W)V \Big].$$

Contracting (3.16) with ξ and using (2.14), (2.15) and (2.20), we have

(3.17)
$$S(U,W) = \left(trh^2 + 1 + \frac{r}{2n}\right)g(U,W) - \left(2n + 1 + \frac{r}{2n}\right)\eta(U)\eta(W).$$

Setting $U = W = e_i$ in (3.17) taking summation over i = 1, 2, ..., (2n+1) we obtain

$$(3.18) tr h^2 = 0.$$

Conversely, from (3.17) it follows that $\hat{K}(U, V)W = 0$.

Case (ii): Suppose M^* is φ -conformally semi-symmetric with respect to $\hat{\nabla}$. Then $\hat{K} \cdot \varphi = 0$, i.e.

(3.19)
$$\hat{K}(U,V)\varphi W - \varphi \hat{K}(U,V)W = 0.$$

From equation (2.23) we have

$$(3.20) \qquad \hat{R}(U,V)\varphi W - \varphi \hat{R}(U,V)W - \frac{1}{2n-1} \Big[\hat{S}(V,\varphi W)U - \hat{S}(U,\varphi W)V + g(V,W)\hat{Q}U - g(U,W)\hat{S}(V,W)\varphi U - \hat{S}(U,W)\varphi V + g(V,W)\varphi \hat{Q}U - g(U,W)\varphi \hat{Q}V \Big] + \frac{\hat{r}}{2n(2n-1)} \Big[g(V,\varphi W)g(U,\varphi W)V - g(V,W)\varphi U + g(U,W)\varphi V \Big] = 0.$$

Contraction of (3.20) with ξ , we get

(3.21)
$$\eta \left(\hat{R}(U, V) \varphi W \right) - \frac{1}{2n-1} \left[\hat{S}(V, \varphi W) \eta(U) - \hat{S}(U, \varphi W) \eta(V) \right]$$
$$+ g(V, W) \eta \left(\hat{Q}U \right) - g(U, W) \eta \left(\hat{Q}V \right) \right] + \frac{\hat{r}}{2n(2n-1)}$$
$$\left[g(V, \varphi W) \eta(U) - g(U, \varphi W) \eta(V) \right] = 0.$$

Taking $V = \xi$ in (3.21) and using (2.16) and (2.21) we have,

(3.22)
$$S(U, \varphi W) = \left(1 + \frac{r}{2n}\right) g(U, \varphi W).$$

Replacing W by φW in (3.22), we have

$$(3.23) S(U,W) = \left(1 + \frac{r}{2n}\right)g(U,W) - \left(1 + \frac{r}{2n} + 2n - trh^2\right)\eta(U)\eta(W).$$

Putting $U = W = e_i$ in (3.23) and summation over i gives

$$(3.24) tr h^2 = 0.$$

Conversely, from (3.23) it follows that $\hat{K} \cdot \varphi = 0$. Therefore the Theorem follows from (3.18) and (3.24).

Theorem 3.3: If in M^* , φh is of Codazzi type then M^* is semi-symmetric.

Proof: If φh is of Codazzi type, i.e.,

(3.25)
$$g((\nabla_U \varphi h)V, Z) - g((\nabla_V \varphi h)U, Z) = 0,$$

then, it follows from (2.8) that

$$(3.26) R(U,Z)\xi = \eta(U)(Z-\varphi hZ)-\eta(Z)(U-\varphi hU).$$

And (2.14) becomes

$$(3.27) \qquad \hat{R}(U,Z)V = 4\Big[g(U,V)Z - g(Z,V)U\Big] + 2\eta(V)$$

$$\Big[\eta(Z)U - \eta(U)Z\Big] + 2\Big[g(Z,V)\eta(U) - g(U,V)\eta(Z)\Big]\xi$$

$$+2\Big[g(\varphi hZ,V)U - g(\varphi hU,V)Z\Big] - \Big[g(U,V)\varphi hZ - g(Z,V)\varphi hU\Big].$$

Consider $\hat{R}(U, Z) \cdot \hat{R} = 0$ i.e.,

(3.28)
$$\left(\hat{R}(U,Z)\right)\hat{R}(V,Y)W = \hat{R}(U,Z)\hat{R}(V,Y)W - \hat{R}(\hat{R}(U,Z)V,Y)W - \hat{R}(V,\hat{R}(U,Z)Y)W - \hat{R}(V,Y)\hat{R}(U,Z)W \right).$$

Taking $Z = W = \xi$ in (3.28) we have

(3.29)
$$(\hat{R}(U,\xi)\hat{R})(V,Y)\xi = \hat{R}(U,\xi)\hat{R}(V,Y)\xi - \hat{R}(\hat{R}(U,\xi)V,Y)\xi$$
$$-\hat{R}(V,\hat{R}(U,\xi)Y)\xi - \hat{R}(V,Y)\hat{R}(U,\xi)\xi .$$

Computing each of four terms of RHS of (3.29) separately and after simplification, we get

$$(3.30) \qquad \hat{R}(U,\xi)\cdot\hat{R}=0.$$

Hence the proof.

Example: Let (x, y, z) are the standard coordinates in R. We consider the 3-dimensional manifold $M = \{(x, y, z) \in R^3\}$. The vector fields $E_1 = \frac{\partial}{\partial x}$, $E_2 = \frac{\partial}{\partial y}$, $\xi = E_3 = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + \frac{\partial}{\partial z}$ form a basis for $T_p M$ at each p in M. We define the Riemannian metric g by,

$$g_{ij} = \begin{cases} 1 \text{ for } i = j \\ 0 \text{ for } i \neq j \end{cases}.$$

Let $\eta(Z) = g(Z, E_3)$ for any $Z \in \chi(M)$. Then $\eta(E_3) = 1$. Let φ be defined by $\varphi(E_1) = E_2$, $\varphi(E_2) = E_1$, $\varphi(E_3) = 0$. We see from the definition of φ and g that $\varphi^2 Z = -Z + \eta(Z) E_3$, $g(\varphi Z, \varphi W) = g(Z, W) - \eta(Z) \eta(W)$, for any vector fields Z and W on M. Thus the structure (φ, ξ, η, g) is an almost contact structure. We also derive that $[E_1, E_3] = E_1, [E_2, E_3] = E_2, [E_1, E_2] = 0$. By Koszul's formula the connection ∇ of g is given by

$$2g(\nabla_{V}U, W) = Vg(U, W) + Ug(W, V) - Wg(V, U)$$
$$-g(V, [U, W]) - g(U, [V, W]) + g(W, [V, U]).$$

By the use of the above formula, we obtain

$$\nabla_{E_1} E_3 = E_1$$
, $\nabla_{E_2} E_3 = E_2$, $\nabla_{E_1} E_1 = -E_3$, $\nabla_{E_2} E_2 = 0$, $\nabla_{E_3} E_3 = 0$, $\nabla_{E_2} E_1 = 0$, $\nabla_{E_3} E_1 = 0$, $\nabla_{E_1} E_2 = 0$, $\nabla_{E_3} E_2 = 0$.

From $h = \frac{1}{2} L_{\varepsilon} \varphi$ and the above equations we see that

$$(3.31) hE_1 = hE_2 = hE_3 = 0.$$

Also we get $\nabla_X \xi = -\varphi^2 X + h\varphi X$ for any $X \in \chi(M)$. Therefore, M is an almost Kenmotsu manifold.

By the above results, we obtain the components of the curvature tensor R as follows:

$$\begin{split} R\Big(E_1,\,E_2\Big)E_3 &= 0\,,\quad R\Big(E_2,\,E_3\Big)E_3 = -E_3\,,\quad R\Big(E_1,\,E_3\Big)E_3 = -E_1\,,\\ R\Big(E_1,\,E_2\Big)E_2 &= -E_1\,,\quad R\Big(E_3,\,E_2\Big)E_2 = E_3\,,\quad R\Big(E_1,\,E_3\Big)E_2 = 0\,,\\ R\Big(E_1,\,E_2\Big)E_1 &= E_2\,,\quad R\Big(E_2,\,E_3\Big)E_1 = 0\,,\quad R\Big(E_1,\,E_3\Big)E_1 = E_3\,. \end{split}$$

Now the semi-symmetric metric connection on M is given by

$$\begin{split} \hat{\nabla}_{E_1} E_3 &= 2E_1, \quad \hat{\nabla}_{E_2} E_3 = 2E_2, \quad \hat{\nabla}_{E_1} E_1 = -2E_3, \quad \hat{\nabla}_{E_2} E_2 = 0, \\ \\ \hat{\nabla}_{E_2} E_3 &= 0, \quad \hat{\nabla}_{E_2} E_1 = 0, \quad \hat{\nabla}_{E_3} E_1 = 0, \quad \hat{\nabla}_{E_1} E_2 = 0, \quad \hat{\nabla}_{E_3} E_2 = 0. \end{split}$$

In view of above relations M is a 3-dimensional almost Kenmotsu manifold which admits semi-symmetric metric connection and

$$\begin{split} \hat{R}\Big(E_1,\,E_2\Big)E_3 &= 0\,,\quad \hat{R}\Big(E_2,\,E_3\Big)E_3 = -2E_3\,,\quad \hat{R}\Big(E_1,\,E_3\Big)E_3 = -2E_1\,,\\ \hat{R}\Big(E_1,\,E_2\Big)E_2 &= -4E_1\,,\quad \hat{R}\Big(E_3,\,E_2\Big)E_2 = -2E_3\,,\quad \hat{R}\Big(E_1,\,E_3\Big)E_2 = 0\,,\\ \hat{R}\Big(E_1,\,E_2\Big)E_1 &= 4E_2\,,\quad \hat{R}\Big(E_2,\,E_3\Big)E_1 = 0\,,\quad \hat{R}\Big(E_1,\,E_3\Big)E_1 = 2E_3\,. \end{split}$$

Making use of the above results we obtain the Ricci tensor as follows:

$$S(E_1, E_1) = g(R(E_1, E_2)E_2, E_1) + g(R(E_1, E_3)E_3, E_1) = -2.$$

Similarly we have

$$S(E_2, E_2) = S(E_3, E_3) = -2$$
, $\hat{S}(E_1, E_1) = -6$ and $\hat{S}(E_3, E_3) = -4$.

$$r = \sum_{i=1}^{3} S(E_i, E_i) = -6 \text{ and } \hat{r} = \sum_{i=1}^{3} \hat{S}(E_i, E_i) = -16.$$

Further we have from the above equations $\hat{R} \cdot \hat{S} = 0$. For instance,

$$(\hat{R}(E_1, E_3) \cdot \hat{S})(E_1, E_1) = 0, (\hat{R}(E_1, E_2) \cdot \hat{S})(E_1, E_1) = 0,$$

$$\left(\hat{R}\left(E_{1}, E_{1}\right) \cdot \hat{S}\right)\left(E_{1}, E_{1}\right) = 0.$$

This is true for other components also. From equation (4.1) we get

$$tr h^2 = \sum_{i=1}^3 g(h^2 E_i, E_i) = 0.$$

Thus Lemma 3.1 is verified.

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