

# On a Quasi-Einstein Kähler Manifold and its Application to General Relativity

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**Abstract:** In the present paper, a quasi-Einstein Kähler manifold is studied. Certain results related to pseudo-projective curvature tensor and  $M$ -projective curvature tensor of a quasi-Einstein Kähler manifold  $(QEK)_4$  have been studied. A  $(QEK)_4$  spacetime with space-matter tensor is also studied and a result on  $(QEK)_4$  spacetime is obtained.

**Keywords:** Quasi-Einstein Kähler manifold, pseudo-projective curvature tensor, energy momentum tensor, Einstein's fields equation, space-matter tensor.

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## 1. Introduction

In 2000, Chaki and Maity<sup>1</sup> introduced the notion of an  $n$ -dimensional Quasi-Einstein manifold and denoted it by  $(QE)_n$ . The study of quasi-Einstein manifolds was further enriched by Chaki<sup>2</sup>, Guha<sup>3</sup>, De and Ghosh<sup>4,5</sup>, Debnath and Konar<sup>6</sup>, Bejan<sup>7</sup> and many others.

Quasi-Einstein manifolds arose during the study of exact solutions of the Einstein field equations as well as during considerations of quasi-umbilical hypersurfaces of semi-Euclidean spaces. For instance, the Robertson-Walker spacetime is a quasi-Einstein manifold. Also, in general relativity<sup>8</sup>, a general quasi-Einstein manifold can be taken as a model of the perfect fluid spacetime. So quasi-Einstein manifolds have some importance in the general theory of relativity.

In this paper, we study quasi-Einstein Kähler manifolds. The paper is organized as follows: Section 1 is introductory. In Section 2, some

geometric properties of quasi-Einstein Kähler manifolds have been studied. Section 3 is devoted to obtain a certain result on quasi-Einstein Kähler manifold in the case of pseudo-projective curvature tensor and in Section 4 in the case of  $M$ -projective curvature tensor. In Section 5, we discuss  $(QEK)_4$  spacetime with space-matter tensor and obtain some results on  $(QEK)_4$  spacetime.

## 2. Preliminaries

Let  $(M_{2n}, g)$  be a  $2n$ -dimensional Kähler manifold with respect to the Levi-Civita connection  $\nabla$ , then we have

$$(2.1) \quad \bar{\bar{X}} + X = 0 \quad \text{and} \quad \bar{X} = FX,$$

$$(2.2) \quad (\nabla_X F) = 0,$$

$$(2.3) \quad g(\bar{X}, \bar{Y}) = g(X, Y),$$

$$(2.4) \quad g(\bar{X}, Y) + g(X, \bar{Y}) = 0,$$

where  $X$  and  $Y$  are arbitrary vector fields. The curvature tensor  $R$  on the Kähler manifold is defined as

$$(2.5) \quad R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z,$$

and it satisfies

$$(2.6) \quad \begin{aligned} \tilde{R}(\bar{X}, \bar{Y}, \bar{Z}, \bar{W}) &= \tilde{R}(X, Y, Z, W) = \tilde{R}(X, Y, \bar{Z}, \bar{W}) \\ &= \tilde{R}(\bar{X}, \bar{Y}, Z, W). \end{aligned}$$

The Ricci tensor satisfies

$$(2.7) \quad S(\bar{X}, \bar{Y}) = S(X, Y).$$

The pseudo-projective curvature tensor  $P$  is defined as

$$(2.8) \quad \begin{aligned} P(X, Y)Z &= aR(X, Y)Z + b[S(Y, Z)X - S(X, Z)Y] \\ &\quad - \frac{r}{n} \left( \frac{a}{n-1} + b \right) [g(Y, Z)X - g(X, Z)Y], \end{aligned}$$

while  $M$  – projective curvature tensor denoted by  $W$ , is defined as

$$(2.9) \quad W(X, Y)Z = R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y \\ + g(Y, Z)QX - g(X, Z)QY].$$

A non-flat Riemannian or a semi-Riemannian manifold  $(M_n, g)$  is called a quasi-Einstein manifold<sup>1</sup> if its Ricci tensor  $S$  is non-vanishing and satisfies the condition

$$(2.10) \quad S(X, Y) = ag(X, Y) + bA(X)A(Y),$$

or equivalently, its Ricci operator  $Q$  satisfies

$$(2.11) \quad QX = aX + bA(X)U,$$

where  $a$  and  $b$  are scalars,  $b \neq 0$  and  $A$  is a non-zero 1-form such that

$$(2.12) \quad g(X, U) = A(X),$$

for all vector fields  $X$  and a unit vector field  $U$ . Contracting  $X$  and  $Y$  in equation (2.10), we get

$$(2.13) \quad r = na + b.$$

In 1972, Chen and Yano<sup>9</sup> introduced the notion of a manifold of quasi-constant curvature. A non-flat Riemannian or a semi-Riemannian manifold is said to be a manifold of quasi-constant curvature if its curvature tensor  $R$  of type  $(0, 4)$  satisfies the condition

$$(2.14) \quad R(X, Y, Z, W) = a[g(Y, Z)g(X, W) - g(X, Z)g(Y, W)] \\ + b[g(Y, Z)A(X)A(W) - g(X, Z)A(Y)A(W) \\ + g(X, W)A(Y)A(Z) - g(Y, W)A(X)A(Z)],$$

where  $a$  and  $b$  are scalars of which  $b \neq 0$  and  $A$  is a non-zero 1-form, such that  $g(X, U) = A(X)$ , for all vector fields  $X$  and a unit vector field  $U$ . Scalars  $a$  and  $b$  appears in (2.14), are called the associated scalars.  $A$  is called associated 1-form and  $U$  is called generator of the manifold. Such an  $n$ -dimensional manifold is denoted by  $(QC)_n$ .

### 3. Pseudo-Projective Curvature Tensor

**Theorem 3.1:** On Quasi-Einstein Kähler manifold  $(QEK)_n$ , the following conditions are equivalent for pseudo-projective curvature tensor:

$$(3.1) \quad P^*(\bar{Y}, \bar{Z}) = P^*(Y, Z)$$

and

$$(3.2) \quad A(\bar{Y})A(Z) + A(Y)A(\bar{Z}) = 0$$

provided  $(n-2)a + (n-1)b \neq 0$ .

**Proof:** From equation (2.8), the pseudo-projective curvature tensor of type (0,4) may be written as

$$(3.3) \quad \begin{aligned} P(X, Y, Z, W) = & aR(X, Y, Z, W) + b[S(Y, Z)g(X, W) \\ & - S(X, Z)g(Y, W)] - \frac{r}{n} \left( \frac{a}{n-1} + b \right) [g(Y, Z)g(X, W) \\ & - g(X, Z)g(Y, W)]. \end{aligned}$$

Using equations (2.10), (2.13) and (2.14) in equation (3.3), we get

$$(3.4) \quad \begin{aligned} P(X, Y, Z, W) = & \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{n-1} + b \right) \right\} [g(Y, Z)g(X, W) \\ & - g(X, Z)g(Y, W)] + b(a+b)[A(Y)A(Z)g(X, W) \\ & - A(X)A(Z)g(Y, W)] + ab[g(Y, Z)A(X)A(W) \\ & - g(X, Z)A(Y)A(W)]. \end{aligned}$$

Contracting equation (3.4) over  $X$  and  $W$ , we get

$$(3.5) \quad \begin{aligned} P^*(Y, Z) = & \left\{ a^2(n-1) + abn - \frac{an+b}{n}(a-b+bn) \right\} g(Y, Z) \\ & + \{ab(n-2) + b^2(n-1)\} A(Y)A(Z) \end{aligned}$$

Replacing  $Y$  and  $Z$  and by  $\bar{Y}$  and  $\bar{Z}$ , and using (2.3) we have

$$(3.6) \quad \begin{aligned} P^*(\bar{Y}, \bar{Z}) = & \left\{ a^2(n-1) + abn - \frac{an+b}{n}(a-b+bn) \right\} g(Y, Z) \\ & + \{ab(n-2) + b^2(n-1)\} A(\bar{Y})A(\bar{Z}), \end{aligned}$$

From equations (3.5) and (3.6), we see that (3.1) holds if and only if

$$(3.7) \quad A(\bar{Y})A(\bar{Z}) = A(Y)A(Z),$$

provided  $(n-2)a + (n-1)b \neq 0$ . Replacing  $Z$  by  $\bar{Z}$  and using (2.1) we get (3.2). Also replacing  $Z$  by  $\bar{Z}$  in (3.2), we get (3.7). Thus (3.2) and (3.7) are equivalent.

**Theorem 3.2:** *On Quasi-Einstein Kähler manifold  $(QEK)_n$ , pseudo-projective curvature tensor satisfies*

$$(3.8) \quad P(\bar{X}, \bar{Y})\bar{Z} = P(\bar{X}, Y)Z + P(X, \bar{Y})Z + P(X, Y)\bar{Z}$$

if

$$(3.9) \quad \begin{aligned} A(\bar{Y})A(\bar{Z})\bar{X} &= A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X \\ &+ A(Y)A(\bar{Z})X. \end{aligned}$$

**Proof:** From equation (3.4), we have

$$(3.10) \quad \begin{aligned} P(X, Y)Z &= \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(Y, Z)X \\ &- g(X, Z)Y] + b(a+b)[A(Y)A(Z)X - A(X)A(Z)Y] \\ &+ ab[g(Y, Z)A(X)U - g(X, Z)A(Y)U]. \end{aligned}$$

Replacing  $X, Y, Z$  by  $\bar{X}, \bar{Y}, \bar{Z}$  in equation (3.10), we get

$$(3.11) \quad \begin{aligned} P(\bar{X}, \bar{Y})\bar{Z} &= \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(\bar{Y}, \bar{Z})\bar{X} \\ &- g(\bar{X}, \bar{Z})\bar{Y}] + b(a+b)[A(\bar{Y})A(\bar{Z})\bar{X} - A(\bar{X})A(\bar{Z})\bar{Y}] \\ &+ ab[g(\bar{Y}, \bar{Z})A(\bar{X})U - g(\bar{X}, \bar{Z})A(\bar{Y})U]. \end{aligned}$$

Using equation (2.3), equation (3.11) may be written as

$$(3.12) \quad \begin{aligned} P(\bar{X}, \bar{Y})\bar{Z} &= \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(Y, Z)\bar{X} \\ &- g(X, Z)\bar{Y}] + b(a+b)[A(\bar{Y})A(\bar{Z})\bar{X} - A(\bar{X})A(\bar{Z})\bar{Y}] \\ &+ ab[g(Y, Z)A(\bar{X})U - g(X, Z)A(\bar{Y})U]. \end{aligned}$$

Replacing  $X$  by  $\bar{X}$  in equation (3.10), we get

$$(3.13) \quad P(\bar{X}, Y)Z = \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(Y, Z)\bar{X} - g(\bar{X}, Z)Y] + b(a+b)[A(Y)A(Z)\bar{X} - A(\bar{X})A(Z)Y] + ab[g(Y, Z)A(\bar{X})U - g(\bar{X}, Z)A(Y)U].$$

Replacing  $Y$  by  $\bar{Y}$  in equation (3.10), we get

$$(3.14) \quad P(X, \bar{Y})Z = \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(\bar{Y}, Z)X - g(X, Z)\bar{Y}] + b(a+b)[A(\bar{Y})A(Z)X - A(X)A(Z)\bar{Y}] + ab[g(\bar{Y}, Z)A(X)U - g(X, Z)A(\bar{Y})U].$$

Replacing  $Z$  by  $\bar{Z}$  in equation (3.10), we get

$$(3.15) \quad P(X, Y)\bar{Z} = \left\{ a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right) \right\} [g(Y, \bar{Z})X - g(X, \bar{Z})Y] + b(a+b)[A(Y)A(\bar{Z})X - A(X)A(\bar{Z})Y] + ab[g(Y, \bar{Z})A(X)U - g(X, \bar{Z})A(Y)U].$$

Adding (3.13), (3.14), (3.15), we get

$$(3.16) \quad P(\bar{X}, Y)Z + P(X, \bar{Y})Z + P(X, Y)\bar{Z} = \{a^2 + ab - \frac{an+b}{n} \left( \frac{a}{(n-1)} + b \right)\} [g(Y, Z)\bar{X} - g(X, Z)\bar{Y}] + b(a+b)[A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X + A(Y)A(\bar{Z})X - A(\bar{X})A(Z)Y - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y] + ab[g(Y, Z)A(\bar{X})U - g(X, Z)A(\bar{Y})U].$$

Using equation (3.12) in (3.16) we get

$$(3.17) \quad P(\bar{X}, Y)Z + P(X, \bar{Y})Z + P(X, Y)\bar{Z} = P(\bar{X}, \bar{Y})\bar{Z} + b(a+b)[A(\bar{X})A(\bar{Z})\bar{Y} - A(\bar{Y})A(\bar{Z})\bar{X} + A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X + A(Y)A(\bar{Z})X - A(\bar{X})A(Z)Y - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y].$$

Suppose (3.9) holds. Interchanging  $X$  and  $Y$  in (3.9), we get

$$(3.18) \quad A(\bar{X})A(\bar{Z})\bar{Y} = A(Y)A(Z)\bar{X} + A(\bar{X})A(Z)Y + A(X)A(\bar{Z})Y.$$

Subtracting (3.18) from (3.9), we get

$$(3.19) \quad \begin{aligned} A(\bar{X})A(\bar{Z})\bar{Y} - A(\bar{Y})A(\bar{Z})\bar{X} &= A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X \\ &\quad + A(Y)A(\bar{Z})X - A(\bar{X})A(Z)Y \\ &\quad - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y \end{aligned}$$

Using (3.19) in (3.17), we get (3.8).

#### 4. $M$ – Projective Curvature Tensor

**Theorem 4.1:** On Quasi-Einstein Kähler manifold  $(QEK)_n$ , the following conditions are equivalent for  $M$  – projective curvature tensor

$$(4.1) \quad W^*(\bar{Y}, \bar{Z}) = W^*(Y, Z).$$

and

$$(4.2) \quad A(\bar{Y})A(\bar{Z}) = A(Y)A(Z)$$

for  $n > 2$ .

**Proof:** From equation (2.9), the  $M$  – projective curvature tensor of type (0,4) may be written as

$$(4.3) \quad \begin{aligned} W(X, Y, Z, W) &= R(X, Y, Z, W) - \frac{1}{2(n-1)}[S(Y, Z)g(X, W) \\ &\quad - S(X, Z)g(Y, W) + g(Y, Z)g(QX, W) - g(X, Z)g(QY, W)]. \end{aligned}$$

Using equations (2.10), (2.11) and (2.14) in equation (4.3), we get

$$(4.4) \quad \begin{aligned} W(X, Y, Z, W) &= \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, Z)g(X, W) - g(X, Z)g(Y, W)] \\ &\quad + \left\{ b - \frac{b}{2(n-1)} \right\} [A(Y)A(Z)g(X, W) - A(X)A(Z)g(Y, W)] \\ &\quad + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, Z)A(X)A(W) - g(X, Z)A(Y)A(W)]. \end{aligned}$$

Contracting equation (4.4) over  $X$  and  $W$ , we get

$$(4.5) \quad W^*(Y, Z) = \left\{ \frac{2an^2 - 2n(3a - b) + 4a - 3b}{2(n-1)} \right\} g(Y, Z) \\ + \left\{ \frac{2n^2b - 7nb + 6b}{2(n-1)} \right\} A(Y)A(Z).$$

Replacing  $Y$  and  $Z$  by  $\bar{Y}$  and  $\bar{Z}$ , and using (2.3), we have

$$(4.6) \quad W^*(\bar{Y}, \bar{Z}) = \left\{ \frac{2an^2 - 2n(3a - b) + 4a - 3b}{2(n-1)} \right\} g(Y, Z) \\ + \left\{ \frac{2n^2b - 7nb + 6b}{2(n-1)} \right\} A(\bar{Y})A(\bar{Z}).$$

From equations (4.5) and (4.6), we have

$$(4.7) \quad W^*(\bar{Y}, \bar{Z}) = W^*(Y, Z) + \left\{ \frac{(2n-3)(n-2)}{2(n-1)} \right\} b[A(\bar{Y})A(\bar{Z}) - A(Y)A(Z)].$$

This shows that (4.1) holds if and only if (4.2) holds for  $n > 2$ .

**Theorem 4.2:** On Quasi-Einstein Kähler manifold  $(QEK)_n$ ,  $M$ -projective curvature tensor satisfies

$$(4.8) \quad W(\bar{X}, \bar{Y})\bar{Z} = W(\bar{X}, Y)Z + W(X, \bar{Y})Z + W(X, Y)\bar{Z}$$

if

$$(4.9) \quad A(\bar{Y})A(\bar{Z})\bar{X} = A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X + A(Y)A(\bar{Z})X.$$

**Proof:** From equation (4.4), we get

$$(4.10) \quad W(X, Y)Z = \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, Z)X - g(X, Z)Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(Y)A(Z)X - A(X)A(Z)Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, Z)A(X)U - g(X, Z)A(Y)U].$$



Replacing  $X, Y, Z$  by  $\bar{X}, \bar{Y}, \bar{Z}$  in equation (4.10), we get

$$(4.11) \quad W(\bar{X}, \bar{Y})\bar{Z} = \left\{ a - \frac{a}{(n-1)} \right\} [g(\bar{Y}, \bar{Z})\bar{X} - g(\bar{X}, \bar{Z})\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(\bar{Y})A(\bar{Z})\bar{X} - A(\bar{X})A(\bar{Z})\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(\bar{Y}, \bar{Z})A(\bar{X})U - g(\bar{X}, \bar{Z})A(\bar{Y})U].$$

Using (2.3) in (4.11), we get

$$(4.12) \quad W(\bar{X}, \bar{Y})\bar{Z} = \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, Z)\bar{X} - g(X, Z)\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(\bar{Y})A(\bar{Z})\bar{X} - A(\bar{X})A(\bar{Z})\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, Z)A(\bar{X})U - g(X, Z)A(\bar{Y})U].$$

Replacing  $X$  by  $\bar{X}$  in equation (4.10), we get

$$(4.13) \quad W(\bar{X}, Y)Z = \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, Z)\bar{X} - g(\bar{X}, Z)Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(Y)A(Z)\bar{X} - A(\bar{X})A(Z)Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, Z)A(\bar{X})U - g(\bar{X}, Z)A(Y)U].$$

Replacing  $Y$  by  $\bar{Y}$  in equation (4.10), we get

$$(4.14) \quad W(X, \bar{Y})Z = \left\{ a - \frac{a}{(n-1)} \right\} [g(\bar{Y}, Z)X - g(X, Z)\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(\bar{Y})A(Z)X - A(X)A(Z)\bar{Y}] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(\bar{Y}, Z)A(X)U - g(X, Z)A(\bar{Y})U].$$

Replacing  $Z$  by  $\bar{Z}$  in equation (4.10), we get

$$(4.15) \quad W(X, Y)\bar{Z} = \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, \bar{Z})X - g(X, \bar{Z})Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(Y)A(\bar{Z})X - A(X)A(\bar{Z})Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, \bar{Z})A(X)U - g(X, \bar{Z})A(Y)U].$$

Adding (4.13), (4.14), (4.15), we get

$$(4.16) \quad W(\bar{X}, Y)Z + W(X, \bar{Y})Z + W(X, Y)\bar{Z} = \left\{ a - \frac{a}{(n-1)} \right\} [g(Y, Z)\bar{X} \\ - g(X, Z)\bar{Y}] + \left\{ b - \frac{b}{2(n-1)} \right\} [A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X \\ + A(Y)A(\bar{Z})X - A(\bar{X})A(Z)Y - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y] \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [g(Y, Z)A(\bar{X})U - g(X, Z)A(\bar{Y})U].$$

Using equation (4.12) in (4.16), we get

$$(4.17) \quad P(\bar{X}, Y)Z + P(X, \bar{Y})Z + P(X, Y)\bar{Z} = P(\bar{X}, \bar{Y})\bar{Z} \\ + \left\{ b - \frac{b}{2(n-1)} \right\} [A(\bar{X})A(\bar{Z})\bar{Y} - A(\bar{Y})A(\bar{Z})\bar{X} \\ + A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X + A(Y)A(\bar{Z})X \\ - A(\bar{X})A(Z)Y - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y].$$

Suppose (4.9) holds. Interchanging  $X$  and  $Y$  in (4.9), we get

$$(4.18) \quad A(\bar{X})A(\bar{Z})\bar{Y} = A(Y)A(Z)\bar{X} + A(\bar{X})A(Z)Y + A(X)A(\bar{Z})Y.$$

Subtracting (4.18) from (4.9), we get

$$(4.19) \quad A(\bar{X})A(\bar{Z})\bar{Y} - A(\bar{Y})A(\bar{Z})\bar{X} = A(Y)A(Z)\bar{X} + A(\bar{Y})A(Z)X \\ + A(Y)A(\bar{Z})X - A(\bar{X})A(Z)Y - A(X)A(Z)\bar{Y} - A(X)A(\bar{Z})Y$$

Using (4.19) in (4.17), we get (4.8).

## 5. $(QEK)_4$ Spacetime

In this section we study space matter-tensor of  $(QEK)_4$  spacetime. In a smooth manifold Petrov<sup>10</sup> defined a tensor  $\tilde{P}$  of type (0,4) as

$$(5.1) \quad \tilde{P} = R + \frac{k}{2} g \wedge T - \sigma G,$$

where  $R$  is the curvature tensor of type (0,4),  $T$  is the energy momentum tensor of type (0,2),  $k$  is the gravitational constant,  $\sigma$  is the energy density and  $G$  is a tensor of type (0,4) given by

$$(5.2) \quad G(X, Y, Z, W) = g(Y, Z)g(X, W) - g(X, Z)g(Y, W),$$

for all  $X, Y, Z, W \in TM$ . Kulkarni-Nomizu product  $g \wedge T$  is given by

$$(5.3) \quad (g \wedge T)(X, Y, Z, W) = g(Y, Z)T(X, W) + g(X, W)T(Y, Z) \\ - g(X, Z)T(Y, W) - g(Y, W)T(X, Z),$$

where  $X, Y, Z, W \in TM$ . The tensor  $\tilde{P}$  is known as the space-matter tensor of type (0,4) of the manifold  $M$ . The space-matter tensor has been studied by Ahasan and Siddiqui<sup>11,12</sup> and many others.

**Theorem 5.1:** *The space-matter tensor in a Quasi-Einstein Kähler spacetime  $(QEK)_4$  obeying Einstein field equation satisfies*

$$(5.4) \quad \tilde{P}^*(\bar{Y}, \bar{Z}) = \tilde{P}^*(Y, Z)$$

if and only if

$$(5.5) \quad A(\bar{Y})A(\bar{Z}) = A(Y)A(Z)$$

for  $b \neq 0$ .

**Proof:** Equation (5.1) can also be written as

$$(5.6) \quad \tilde{P}(X, Y, Z, W) = R(X, Y, Z, W) + \frac{k}{2} [g(Y, Z)T(X, W) \\ + g(X, W)T(Y, Z) - g(X, Z)T(Y, W) - g(Y, W)T(X, Z)] \\ - \sigma [g(Y, Z)g(X, W) - g(X, Z)g(Y, W)].$$

The Einstein's field equation without cosmological constant is given by

$$(5.7) \quad S(X, Y) - \frac{r}{2} g(X, Y) = kT(X, Y),$$

where  $k$  is the gravitational constant and  $r$  is the scalar curvature of the spacetime.

Using equations (2.10), (2.14) and (5.7) in equation (5.6), we get

$$(5.8) \quad \begin{aligned} \tilde{P}(X, Y, Z, W) = & \left\{ a + \sigma + \frac{a(2-n)+b}{2} \right\} [g(Y, Z)g(X, W) \\ & - g(X, Z)g(Y, W)] + \frac{3b}{2} [A(Y)A(Z)g(X, W) \\ & - A(X)A(Z)g(Y, W)] + \frac{b}{2} [g(Y, Z)A(X)A(W) \\ & - g(X, Z)A(Y)A(W)]. \end{aligned}$$

Contracting equation (5.8) over  $X$  and  $W$ , we get

$$(5.9) \quad \tilde{P}^*(Y, Z) = \left\{ \frac{12a + 6\sigma - 3an + 4b}{2} \right\} g(Y, Z) + 4bA(Y)A(Z).$$

Replacing  $Y$  and  $Z$  and by  $\bar{Y}$  and  $\bar{Z}$  in (5.9), we have

$$(5.10) \quad \tilde{P}^*(\bar{Y}, \bar{Z}) = \left\{ \frac{12a + 6\sigma - 3an + 4b}{2} \right\} g(Y, Z) + 4bA(\bar{Y})A(\bar{Z}),$$

for  $g(\bar{Y}, \bar{Z}) = g(Y, Z)$ . From equations (5.9) and (5.10), we see that (5.4) holds if and only if (5.5) holds for  $b \neq 0$ .

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